

# FREC deliverable 8: Algebraic classification of recognizable sets of $\lambda$ -terms

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**Abstract.** This document constitutes the 8th deliverable of the FREC ANR project. So as to foster our understanding the nature of finite recognizability in the context of  $\lambda Y$ -calculus, this report presents the construction of a model that allows one to account for some computational properties of  $\lambda Y$ -terms: here namely the convergence of  $\beta\delta$ -conversion. The computational properties of finite state models are usually absent from the realm of recognizability. Taking those properties into account and relating them to syntactic properties of Böhm trees is a first step towards the understanding of a classification of the expressive power of finitary models of  $\lambda Y$ -calculus.

We propose a model-based approach to the model checking problem for recursive schemes. Since simply typed lambda calculus with the fixpoint operator,  $\lambda Y$ -calculus, is equivalent to schemes, we propose the use of a model of  $\lambda Y$  to discriminate the terms that satisfy a given property. If a model is finite in every type, this gives a decision procedure. We provide a construction of such a model for every property expressed by automata with trivial acceptance conditions and divergence testing. Such properties pose already interesting challenges for model construction. Moreover, we argue that having models capturing some class of properties has several other virtues in addition to providing decidability of the model-checking problem. As an illustration, we show a very simple construction transforming a scheme to a scheme reflecting a property captured by a given model.

## 1 Introduction

We are interested in the relation between the effective denotational semantics of the simply typed  $\lambda Y$ -calculus and the logical properties of Böhm trees. By *effective denotational* semantics we mean semantic spaces in which the denotation of a term can be computed; in this paper, these effective denotational semantics will simply be finite models of the  $\lambda Y$ -calculus, but  $Y$  will often be interpreted neither as the least nor as the greatest fixpoint.

Understanding properties of Böhm trees from a logical point of view is a problem that arises naturally in the model checking of higher-order programs. Often this problem is presented in the context of higher-order recursive schemes that generate a possibly infinite tree. Nevertheless, higher-order recursive schemes can be represented faithfully by  $\lambda Y$ -terms, in the sense that the infinite trees they generate are precisely the Böhm trees  $\lambda Y$ -terms define.

The technical question we address here is whether the Böhm tree of a given term is accepted by a given tree automaton. We consider only automata with trivial acceptance conditions which we call *TAC automata*. The principal technical challenge we face is that we allow automata to detect if a term has a head normal form. We call such automata *insightful* as opposed to  $\Omega$ -blind automata that are insensitive to divergence. For example, the models studied by Aehlig or Kobayashi [Aeh07,Kob09b] are  $\Omega$ -blind. The construction of a model of the  $\lambda Y$ -calculus that can at the same time represent safety properties (as defined by trivial automata) and check whether a computation is diverging is truly challenging. Indeed, non-convergence has to have a non-standard interpretation, and this affects strongly the way the meanings of terms is computed. As we show here,  $Y$  combinators cannot be interpreted as an extremal fixpoint in this case, so known algorithms for verification of safety properties cannot take non-convergence into account in a non-trivial way.

Let us explain the difference between insightful and  $\Omega$ -blind conditions. The definition of a Böhm tree says that if the head reduction of a term does not terminate then in the resulting tree we get a special symbol  $\Omega$ . Yet this is not how this issue is treated in all known solutions to the model-checking problem. There, instead of reading  $\Omega$  the automaton is allowed to run on the infinite sequence of unproductive reductions. In the case of automata with trivial conditions, this has as an immediate consequence that such an infinite computation is accepted by the automaton. From a denotational semantics perspective, this amounts to interpreting the fixpoint combinator  $Y$  as a greatest fixpoint on some finite monotonous model. So, for example, with this approach to semantics, the language of schemes that produce at least one head symbol is not definable by automata with trivial conditions. Let us note that this problem disappears once we consider Büchi conditions as they permit one to detect an infinite unproductive execution. So here we look at a particular class of properties expressible by Büchi conditions. Thus, the problem we address is a non-trivial extension of what is usually understood as verification of safety properties for recursive schemes.

Our starting point is the proof that the usual methods for treating the safety properties of higher-order schemes cannot capture the properties described with insightful automata. The first result of the paper shows that extremal fixpoint models can only capture boolean combinations of  $\Omega$ -blind TAC automata. Our main result is the construction of a model capturing insightful automata. This construction is based on an interpretation of the fixpoint operator which is neither the greatest nor the least one. The main difficulty is to obtain a definition that guaranties the existence and uniqueness of the fixpoint at every type.

In our opinion providing models capturing certain classes of properties is an important problem both from foundational and practical points of view. On the theoretical side, models need to handle all the constructions of the  $\lambda$ -calculus while, for example, the type systems proposed so far by Kobayashi [Kob09b], and by Kobayashi and Ong [KO09] do not cater for  $\lambda$ -abstraction. Moreover, the treatment of recursion is performed by means of a parity game that is not

incorporated to the type system. In contrast we interpret the  $Y$  combinator as an element of the model we construct. In consequence the model-based approach gives more insight into the solution. On the practical side, models capturing classes of properties set the stage to define algorithms to decide these properties in terms of evaluating  $\lambda$ -terms in them. One can remark that models offer most of the algorithmic advantages of other approaches. As illustrated by [SMGB12], the typing discipline of [Kob09b] can be completely rephrased in terms of simple models. This practical interest of models has been made into a slogan by Terui [Ter12]: *better semantics, faster computation*. To substantiate further the interest of models we also present a straightforward transformation of a scheme to a scheme reflecting a given property [BCOS10]. From a wider perspective, the model based approach opens a new bridge between the  $\lambda$ -calculus and model-checking communities. In particular the model we construct for insightful automata brings into the front stage particular non-extremal fixpoints. To our knowledge these have not been studied much in the  $\lambda$ -calculus literature.

**Related work** The model checking problem has been solved by Ong [Ong06] and subsequently revisited in a number of ways [HMOS08,KO09,SW11]. A much simpler proof for the same problem in the case of  $\Omega$ -blind TAC automata has been given by Aehlig [Aeh07]. In his influential work, Kobayashi [Kob09b,Kob09a,Kob09c] has shown that many interesting properties of higher-order recursive programs can be analyzed with recursive schemes and  $\Omega$ -blind TAC automata. He has also proposed an intersection type system for the model-checking problem. The method has been applied to the verification of higher-order programs [Kob11]. Another method based on higher-order collapsible pushdown automata uses invariants expressed in terms of regular properties of higher-order stacks that is close in spirit to intersection types [BCHS12]. Let us note that at present all algorithmic effort concentrates on  $\Omega$ -blind TAC automata. In a recent work Ong and Tsukada [OT12] provide a game semantics model corresponding to Kobayashi’s style type system. Their model can handle only  $\Omega$ -blind automata, but then, thanks to game semantics, it is fully abstract. We cannot hope to have full abstraction in our approach using simple constructions; moreover it is well-known that it is in general not possible to effectively construct fully abstract models even in the finite case [Loa01]. In turn, as we mention in [Wal12] and show here, handling  $\Omega$ -blind automata with simple models is straightforward. The reflection property for schemes has been proved by Broadbent et. al. [BCOS10]. Haddad gives a direct transformation of a scheme to an equivalent scheme without divergent computations [Had12].

**Organization of the paper** The next section introduces the objects of our study:  $\lambda Y$ -calculus and automata with trivial acceptance conditions (TAC automata). In Section 3 we present the correspondence between models of  $\lambda Y$  with greatest fixpoints and boolean combinations of  $\Omega$ -blind TAC automata. In Section 4 we give the construction of the model for insightful TAC automata. The last section presents a transformation of a term into a term reflecting a given property.

## 2 Preliminaries

The two basic objects of our study are:  $\lambda Y$ -calculus and TAC automata. We will look at  $\lambda Y$ -terms as mechanisms for generating infinite trees that are then accepted or rejected by a TAC automaton. The definitions we adopt are standard ones in the  $\lambda$ -calculus and automata theory. The only exceptions are the notion of a tree signature used to simplify the presentation and the notion of  $\Omega$ -blind/insightful automata that are specific to this paper.

### 2.1 $\lambda Y$ -calculus and models

The *set of types*  $\mathcal{T}$  is constructed from a unique *basic type* 0 using a binary operation  $\rightarrow$ . Thus 0 is a type and if  $\alpha, \beta$  are types, so is  $(\alpha \rightarrow \beta)$ . The order of a type is defined by:  $order(0) = 0$ , and  $order(\alpha \rightarrow \beta) = \max(1 + order(\alpha), order(\beta))$ . We assume that the symbol  $\rightarrow$  associates to the right. More specifically we shall write  $\alpha_1 \rightarrow \dots \rightarrow \alpha_n \rightarrow \beta$  so as to denote the type  $(\alpha_1 \rightarrow (\dots (\alpha_{n-1} \rightarrow (\alpha_n \rightarrow \beta)) \dots))$ .

A *signature*, denoted  $\Sigma$ , is a set of typed constants, *i.e.* symbols with associated types from  $\mathcal{T}$ . We will assume that for every type  $\alpha \in \mathcal{T}$  there are constants  $\omega^\alpha$ ,  $\Omega^\alpha$  and  $Y^{(\alpha \rightarrow \alpha) \rightarrow \alpha}$ . A constant  $Y^{(\alpha \rightarrow \alpha) \rightarrow \alpha}$  will stand for a fixpoint operator. Both  $\omega^\alpha$  and  $\Omega^\alpha$  will stand for undefined, but we will need two such constants in Section 4. Of special interest to us will be *tree signatures* where all constants other than  $Y$ ,  $\omega$  and  $\Omega$  have order at most 1. Observe that types of order 1 have the form  $0^i \rightarrow 0$  for some  $i$ ; the latter is a short notation for  $0 \rightarrow 0 \rightarrow \dots \rightarrow 0 \rightarrow 0$ , where there are  $i + 1$  occurrences of 0.

**Proviso:** To simplify the notation we will suppose that all the constants in a tree signature are either of type 0 or of type  $0 \rightarrow 0 \rightarrow 0$ . So they are either a constant of the base type or a function of two arguments over the base type. This assumption does not influence the results of the paper.

The set of *simply typed  $\lambda$ -terms* is defined inductively as follows. A constant of type  $\alpha$  is a term of type  $\alpha$ . For each type  $\alpha$  there is a countable set of variables  $x^\alpha, y^\alpha, \dots$  that are also terms of type  $\alpha$ . If  $M$  is a term of type  $\beta$  and  $x^\alpha$  a variable of type  $\alpha$  then  $\lambda x^\alpha.M$  is a term of type  $\alpha \rightarrow \beta$ . Finally, if  $M$  is of type  $\alpha \rightarrow \beta$  and  $N$  is a term of type  $\alpha$  then  $MN$  is a term of type  $\beta$ . We shall use the usual convention about dropping parentheses in writing  $\lambda$ -terms and we shall write sequences of  $\lambda$ -abstractions  $\lambda x_1 \dots \lambda x_n.M$  with only one  $\lambda$ :  $\lambda x_1 \dots \lambda x_n.M$ . Even shorter, we shall write  $\lambda \mathbf{x}.M$  when  $\mathbf{x}$  stands for a sequence of variables.

The usual operational semantics of the  $\lambda$ -calculus is given by  $\beta$ -contraction. To give the meaning to fixpoint constants we use  $\delta$ -contraction ( $\rightarrow_\delta$ ). Of course those rules may be applied at any position in a term.

$$(\lambda x.M)N \rightarrow_\beta M[N/x] \quad YM \rightarrow_\delta M(YM).$$

We write  $\rightarrow_{\beta\delta}^*$  for the  $\beta\delta$ -reduction, the reflexive and transitive closure of the sum of the two relations (we write  $\rightarrow_{\beta\delta}^+$  for its transitive closure). This relation defines

an operational equality on terms. We write  $=_{\beta\delta}$  for the smallest equivalence relation containing  $\rightarrow_{\beta\delta}^*$ . It is called  $\beta\delta$ -conversion or  $\beta\delta$ -equality. Given a term  $M = \lambda x_1 \dots x_n. N_0 N_1 \dots N_p$  where  $N_0$  is of the form  $(\lambda x.P)Q$  or  $YP$ , then  $N_0$  is called the *head redex* of  $M$ . We write  $M \rightarrow_h M'$  when  $M'$  is obtained by  $\beta\delta$ -contracting the head redex of  $M$  (when it has one). We write  $\rightarrow_h^*$  and  $\rightarrow_h^+$  respectively for the reflexive and transitive closure and the transitive closure of  $\rightarrow_h$ . The relation  $\rightarrow_h^*$  is called *head reduction*. A term with no head redex is said to be in *head normal form*.

Thus, the operational semantics of the  $\lambda Y$ -calculus is the  $\beta\delta$ -reduction. It is well-known that this semantics is confluent and enjoys subject reduction (*i.e.* the type of terms is invariant under  $\beta\delta$ -reduction). So every term has at most one normal form, but due to  $\delta$ -reduction there are terms without a normal form. A term may not have a normal form because it does not have head normal form, in such case it is called *unsolvable*. Even if a term has a head normal form, *i.e.* it is *solvable*, it may contain an unsolvable subterm that prevents it from having a normal form. Finally, it may be also the case that all the subterms of a term are solvable but the reduction generates an infinitely growing term. It is thus classical in the  $\lambda$ -calculus to consider a kind of infinite normal form that by itself is an infinite tree, and in consequence it is not a term of  $\lambda Y$  [Bar84,AC98]. This infinite normal form is called *Böhm tree*.

A *Böhm tree* is an unranked, ordered, and potentially infinite tree with nodes labeled by terms of the form  $\lambda x_1 \dots x_n. N$ ; where  $N$  is a variable or a constant, and the sequence of  $\lambda$ -abstractions is optional. So for example  $x^0$ ,  $\Omega^0$ ,  $\lambda x^0. \omega^0$  are labels, but  $\lambda y^0. x^{0 \rightarrow 0} y^0$  is not.

**Definition 1.** A Böhm tree of a term  $M$  is obtained in the following way.

- If  $M \rightarrow_{\beta\delta}^* \lambda \mathbf{x}. N_0 N_1 \dots N_k$  with  $N_0$  a variable or a constant then  $BT(M)$  is a tree having root labeled by  $\lambda \mathbf{x}. N_0$  and having  $BT(N_1), \dots, BT(N_k)$  as subtrees.
- Otherwise  $BT(M) = \Omega^\alpha$ , where  $\alpha$  is the type of  $M$ .

Observe that a term  $M$  without the constants  $\Omega$  and  $\omega$  has a  $\beta\delta$ -normal form if and only if  $BT(M)$  is a finite tree without the constants  $\Omega$  and  $\omega$ . In this case the Böhm tree is just another representation of the normal form. Unlike in the standard theory of the simply typed  $\lambda$ -calculus we will be rather interested in terms with infinite Böhm trees.

Recall that in a tree signature all constants except of  $Y$ ,  $\Omega$ , and  $\omega$  are of type 0 or  $0 \rightarrow 0 \rightarrow 0$ . A closed term without  $\lambda$ -abstraction and  $Y$  over such a signature is just a finite binary tree, where constants of type 0 occur at leaves, and constants of type  $0 \rightarrow 0 \rightarrow 0$  are in the internal nodes. The same holds for Böhm trees:

**Lemma 1.** If  $M$  is a closed term of type 0 over a tree signature then  $BT(M)$  is a potentially infinite binary tree.

We will consider finitary models of the  $\lambda Y$ -calculus. In the first part of the paper we will concentrate on those where  $Y$  is interpreted as the greatest fixpoint (those with least fixpoints are just dual to these ones).

**Definition 2.** A GFP-model of a signature  $\Sigma$  is a tuple  $\mathcal{S} = \langle \{\mathcal{S}_\alpha\}_{\alpha \in \mathcal{T}}, \rho \rangle$  where  $\mathcal{S}_0$  is a finite lattice, called the base set of the model, and for every type  $\alpha \rightarrow \beta \in \mathcal{T}$ ,  $\mathcal{S}_{\alpha \rightarrow \beta}$  is the lattice  $\text{mon}[\mathcal{S}_\alpha \rightarrow \mathcal{S}_\beta]$  of monotone functions from  $\mathcal{S}_\alpha$  to  $\mathcal{S}_\beta$  ordered coordinatewise. The valuation function  $\rho$  is required to satisfy certain conditions:

- If  $c \in \Sigma$  is a constant of type  $\alpha$  then  $\rho(c)$  is an element of  $\mathcal{S}_\alpha$ .
- For every  $\alpha \in \mathcal{T}$ , both  $\rho(\omega^\alpha)$  and  $\rho(\Omega^\alpha)$  are the greatest elements of  $\mathcal{S}_\alpha$ .
- Moreover,  $\rho(Y^{(\alpha \rightarrow \alpha) \rightarrow \alpha})$  is the function assigning to every function  $f \in \mathcal{S}_{\alpha \rightarrow \alpha}$  its greatest fixpoint.

Observe that every  $\mathcal{S}_\alpha$  is finite, hence all the greatest fixpoints exist without any additional assumptions on the lattice.

A *variable assignment* is a function  $v$  associating to a variable of type  $\alpha$  an element of  $\mathcal{S}_\alpha$ . If  $s$  is an element of  $\mathcal{S}_\alpha$  and  $x^\alpha$  is a variable of type  $\alpha$  then  $v[s/x^\alpha]$  denotes the valuation that assigns  $s$  to  $x^\alpha$  and that is identical to  $v$  everywhere else.

The *interpretation of a term*  $M$  of type  $\alpha$  in the model  $\mathcal{S}$  under the valuation  $v$  is an element of  $\mathcal{S}_\alpha$  denoted  $\llbracket M \rrbracket_{\mathcal{S}}^v$ . The meaning is defined inductively:

- $\llbracket c \rrbracket_{\mathcal{S}}^v = \rho(c)$
- $\llbracket x^\alpha \rrbracket_{\mathcal{S}}^v = v(x^\alpha)$
- $\llbracket MN \rrbracket_{\mathcal{S}}^v = \llbracket M \rrbracket_{\mathcal{S}}^v (\llbracket N \rrbracket_{\mathcal{S}}^v)$
- $\llbracket \lambda x^\alpha. M \rrbracket_{\mathcal{S}}^v$  is a function mapping an element  $s \in \mathcal{S}_\alpha$  to  $\llbracket M \rrbracket_{\mathcal{S}}^{v[s/x^\alpha]}$  that by abuse of notation we may write  $\lambda s. \llbracket M \rrbracket_{\mathcal{S}}^{v[s/x^\alpha]}$ .

As usual, we will omit subscripts or superscripts in the notation of the semantic function if they are clear from the context.

Of course a GFP model is sound with respect to  $\beta\delta$ -conversion. Hence two  $\beta\delta$ -convertible terms have the same semantics in the model. For us it is important that a stronger property holds: if two terms have the same Böhm trees then they have the same semantics in the model. For this we need to formally define the semantics of a Böhm tree.

The semantics of a Böhm tree is defined in terms of its truncations. For every  $n \in \mathbb{N}$ , we denote by  $BT(M) \downarrow_n$  the finite term that is the result of replacing in the tree  $BT(M)$  every subtree at depth  $n$  by the constant  $\omega^\alpha$  of the appropriate type. Observe that if  $M$  is closed and of type 0 then  $\alpha$  will always be the base type 0. This is because we work with a tree signature. We define

$$\llbracket BT(M) \rrbracket_{\mathcal{S}}^v = \bigwedge \{ \llbracket BT(M) \downarrow_n \rrbracket_{\mathcal{S}}^v \mid n \in \mathbb{N} \}.$$

The above definitions are standard for  $\lambda Y$ -calculus, or more generally for PCF [AC98]. In particular the following proposition, in a more general form, can be found as Exercise 6.1.8 in op. cit<sup>1</sup>.

<sup>1</sup> In this paper we work with models built with finite lattices and monotone which are a particular case of the directed complete partial order and continuous functions used in [AC98].

**Proposition 1.** *If  $\mathcal{S}$  is a finite GFP-model and  $M$  is a closed term then:  $\llbracket M \rrbracket_{\mathcal{S}} = \llbracket BT(M) \rrbracket_{\mathcal{S}}$ .*

Observe that  $\Omega$  is used to denote divergence and  $\omega$  is used in the definition of truncation  $BT(M) \downarrow_n$ . In GFP-models this is irrelevant as the two constants are required to have the same meaning. Later we will consider models that distinguish those two constants.

## 2.2 TAC Automata

Let us fix a tree signature  $\Sigma$ . Recall that this means that apart from  $\omega$ ,  $\Omega$  and  $Y$  all constants have order at most 2. According to our proviso from page 4 all constants in  $\Sigma$  have either type 0 or type  $0 \rightarrow 0 \rightarrow 0$ . In this case, as we only consider closed terms of type 0, by Lemma 1, Böhm trees are potentially infinite binary trees. Let  $\Sigma_0$  be the set of constants of type 0, and  $\Sigma_2$  the set of constants of type  $0 \rightarrow 0 \rightarrow 0$ .

**Definition 3.** *A finite tree automaton with trivial acceptance condition (TAC automaton) over the signature  $\Sigma = \Sigma_0 \cup \Sigma_2$  is*

$$\mathcal{A} = \langle Q, \Sigma, q^0 \in Q, \delta_0 : Q \times (\Sigma_0 \cup \{\Omega\}) \rightarrow \{\text{ff}, \text{tt}\}, \delta_2 : Q \times \Sigma_2 \rightarrow \mathcal{P}(Q^2) \rangle$$

where  $Q$  is a finite set of states and  $q^0 \in Q$  is the initial state. The transition function of TAC automaton may be the subject to the additional restriction:

$$\Omega\text{-blind: } \delta_0(q, \Omega) = \text{tt for all } q \in Q.$$

An automaton satisfying this restriction is called  $\Omega$ -blind. For clarity, we use the term insightful to refer to automata without this restriction.

Automata are used to define language of possibly infinite binary trees. More specifically an automaton over  $\Sigma$  shall define a set of  $\Sigma$ -labelled binary trees. These trees are partial functions  $t : \{1, 2\}^* \rightarrow \Sigma \cup \{\Omega\}$  such that their domain is a binary tree: (i) if  $uv$  is in the domain of  $t$  then so is  $u$ , (ii) if  $u$  is in the domain of  $t$  and  $t(u)$  is in  $\Sigma_2$  then  $u1$  and  $u2$  are in the domain of  $t$ , (iii) if  $u$  is in the domain of  $t$  and  $t(u) \in \Sigma_0 \cup \{\Omega\}$  then  $u$  is called a *leaf*, and if  $uv$  is in the domain of  $t$  then  $v$  is the empty string.

A *run* of  $\mathcal{A}$  on  $t$  is a mapping  $r : \{1, 2\}^* \rightarrow Q$  with the same domain as  $t$  and such that:

- $r(\varepsilon) = q^0$ , here  $\varepsilon$  is the root of  $t$ .
- $(r(u1), r(u2)) \in \delta_2(t(u), r(u))$  if  $u$  is an internal node.

A run is *accepting* if  $\delta_0(r(u), t(u)) = \text{tt}$  for every leaf  $u$  of  $t$ . A tree is *accepted* by  $\mathcal{A}$  if there is an accepting run on the tree. The *language* of  $\mathcal{A}$ , denoted  $L(\mathcal{A})$ , is the set of trees that are accepted by  $\mathcal{A}$ .

Observe that TAC automata have acceptance conditions on leaves, expressed with  $\delta_0$ , but do not have acceptance conditions on infinite paths.

As underlined in the introduction, all the previous works on automata with trivial conditions rely on the  $\Omega$ -blind restriction. Let us give some examples of properties that can be expressed with insightful automata but not with  $\Omega$ -blind automata.

- The set of terms not having  $\Omega$  in their Böhm tree. To recognize this set we take the automaton with a unique state  $q$ . This state has transitions on all the letters from  $\Sigma_2$ . It also can end a run in every constant of type 0 except for  $\Omega$ : this means  $\delta_0(q, \Omega) = ff$  and  $\delta_0(q, c) = tt$  for all other  $c$ .
- The set of terms having a head normal form. We take an automaton with two states  $q$  and  $q_\top$ . From  $q_\top$  the automaton accepts every tree. From  $q$  it has transitions to  $q_\top$  on all the letters from  $\Sigma_2$ , on letters from  $\Sigma_0$  it behaves as the automaton above.
- Building on these two examples one can easily construct an automaton for a property like “every occurrence of  $\Omega$  is preceded by a constant *err*”.

It is easy to see that none of these languages is recognized by any  $\Omega$ -blind automaton since if such an automaton accepts a tree  $t$  then it accepts also every tree obtained by replacing a subtree of  $t$  by  $\Omega$ . This observation also allows to show that those languages cannot be defined as boolean combinations of  $\Omega$ -blind automata.

### 3 GFP models and $\Omega$ -blind TAC automata

In this section we show that the recognizing power of GFP models coincides with that of boolean combinations of  $\Omega$ -blind TAC automata. For every automaton we will construct a model capable of discriminating the terms accepted by the automaton. For the opposite direction, we will use boolean combinations of TAC automata to capture the recognizing power of the model. We start with the expected formal definition of a set of  $\lambda Y$ -terms recognized by a model.

**Definition 4.** *For a GFP model  $\mathcal{S}$  over the base set  $\mathcal{S}_0$ . The language recognized by a subset  $F \subseteq \mathcal{S}_0$  is the set of closed  $\lambda Y$ -terms  $\{M \mid \llbracket M \rrbracket_{\mathcal{S}} \in F\}$ .*

We now give some notations that we shall use in the course of the proofs. Given a closed term  $M$  of type 0, the tree  $BT(M)$  can be seen as a binary tree  $t : \{1, 2\}^* \rightarrow \Sigma$ . For every node  $v$  in the domain of  $t$ , we write  $M_v$  for the subtree of  $t$  rooted at node  $v$ . The tree  $BT(M) \downarrow_k$  is a prefix of this tree containing nodes up to depth  $k$ , denote it  $t_k$ . Every node  $v$  in the domain of  $t_k$  corresponds to a subterm of  $BT(M) \downarrow_k$  that we denote  $M_v^k$ . In particular  $M_\varepsilon^k$  is  $BT(M) \downarrow_k$  since  $\varepsilon$  is the root of  $BT(M) \downarrow_k$ .

**Proposition 2.** *For every  $\Omega$ -blind TAC automaton  $\mathcal{A}$ , the language of  $\mathcal{A}$  is recognized by a GFP model.*

*Proof.* For the model  $\mathcal{S}_{\mathcal{A}}$  in question we take a GFP model with the base set  $\mathcal{S}_0 = \mathcal{P}(Q)$ . This determines  $\mathcal{S}_\alpha$  for every type  $\alpha$ . It remains to define the

interpretation of constants other than  $\omega$ ,  $\Omega$ , or  $Y$ . A constant  $c$  of type 0 is interpreted as a set  $\{q \mid \delta_0(q, c) = tt\}$ . A constant  $a$  of type  $0 \rightarrow 0 \rightarrow 0$  is interpreted as a function whose value on  $(S_0, S_1) \in \mathcal{P}(Q)^2$  is  $\{q \mid \delta_2(q, a) \cap S_0 \times S_1 \neq \emptyset\}$ . Finally, for the set  $F_{\mathcal{A}}$  used to recognize  $L(\mathcal{A})$  we will take  $\{S \mid q^0 \in S\}$ ; recall that  $q^0$  is the initial state of  $\mathcal{A}$ . We want to show that for every closed term  $M$  of type 0:

$$BT(M) \in L(\mathcal{A}) \quad \text{iff} \quad \llbracket M \rrbracket \in F_{\mathcal{A}}.$$

For the direction from left to right, we take a  $\lambda Y$ -term  $M$  such that  $BT(M) \in L(\mathcal{A})$ , and show that  $q^0 \in \llbracket BT(M) \rrbracket$ . This will do as  $\llbracket BT(M) \rrbracket = \llbracket M \rrbracket$  by Proposition 1. Recall that  $\llbracket BT(M) \rrbracket = \bigwedge \{\llbracket BT(M) \downarrow_k \rrbracket \mid k = 1, 2, \dots\}$ . So it is enough to show that  $q^0 \in \llbracket BT(M) \downarrow_k \rrbracket$  for every  $k$ .

Let us assume that we have an accepting run  $r$  of  $\mathcal{A}$  on  $BT(M)$ . By induction on the height of  $v$  in the domain of  $BT(M) \downarrow_k$  we show that  $r(v) \in \llbracket M_v^k \rrbracket$ . The desired conclusion will follow by taking  $v = \varepsilon$ ; that is the root of the tree. If  $v$  is a ‘‘cut leaf’’ then  $M_v^k$  is  $\omega^0$ . So  $r(v) \in \llbracket \omega^0 \rrbracket$  since  $\llbracket \omega^0 \rrbracket = Q$ . If  $v$  is a ‘‘non-converging leaf’’, then  $M_v^k$  is  $\Omega^0$  and  $r(v) \in Q = \llbracket \Omega^0 \rrbracket$ . If  $v$  is a ‘‘normal’’ leaf then  $M_v^k$  is a constant  $c$  of type 0. We have  $r(v) \in \{q \mid \delta(q, c) = tt\}$ . If  $v$  is an internal node then  $M_v^k = aM_{v_1}^k M_{v_2}^k$ . By induction assumption  $r(v_1) \in \llbracket M_{v_1}^k \rrbracket$  and  $r(v_2) \in \llbracket M_{v_2}^k \rrbracket$ . Hence by definition of  $\rho(a)$  we get

$$r(v) \in \llbracket M_v \rrbracket = \rho(a)(\llbracket M_{v_1}^k \rrbracket, \llbracket M_{v_2}^k \rrbracket) .$$

For the direction from right to left we take a term  $M$  and a state  $q \in \llbracket M \rrbracket$ . We construct a run of  $\mathcal{A}$  on  $BT(M)$  that starts with the state  $q$ . So we put  $r(\varepsilon) = q$ . By Proposition 1, we know that  $q \in \llbracket BT(M) \downarrow_k \rrbracket$  for all  $k$ . There is a letter  $a$  such that every term  $BT(M) \downarrow_k$  is either of the form  $\omega$  or  $\Omega$  or  $aM_1^k M_2^k$ . In case it is of the form  $\Omega$ , then the conclusion follows immediately since the automaton is  $\Omega$ -blind. In case it is of the form  $aM_1^k M_2^k$ , since  $\delta(q, a)$  is a finite set of pairs, there is a pair  $(q_1, q_2) \in \delta(q, a)$  such that  $q_1 \in \llbracket M_1^k \rrbracket$  and  $q_2 \in \llbracket M_2^k \rrbracket$  for infinitely many  $k$ . We repeat the argument with the state  $q_1$  from node 1 and with the state  $q_2$  from node 2. It is easy to see that this gives an accepting run of  $\mathcal{A}$  on  $BT(M)$ .

As we are now going to see, the power of GFP models is characterized by  $\Omega$ -blind TAC automata. We will show that every language recognized by a GFP model is a boolean combination of languages of  $\Omega$ -blind TAC automata. For the rest of the subsection we fix a tree signature  $\Sigma$  and a GFP model  $\mathcal{S} = \langle \{\mathcal{S}_\alpha\}_{\alpha \in \mathcal{T}}, \rho \rangle$  over  $\Sigma$ .

We construct a family of automata that reflect the model  $\mathcal{S}$ . We let  $Q$  be equal to the base set  $\mathcal{S}_0$  of the model. We define  $\delta_0 : Q \times (\Sigma_0 \cup \{\Omega\}) \rightarrow \{ff, tt\}$  and  $\delta_1 : Q \times \Sigma_2 \rightarrow \mathcal{P}(Q^2)$  to be the functions such that:

$$\begin{aligned} \delta_0(q, a) = tt & \quad \text{iff} \quad q \leq \rho(a) & \quad (\text{in the order of } \mathcal{S}_0) \\ \delta_1(q, a) = \{(q_1, q_2) \mid q \leq \rho(a)(q_1, q_2)\}. \end{aligned}$$

For  $q$  in  $Q$ , we define  $\mathcal{A}_q$  to be the automaton with the starting state  $q$  and the other components as above:

$$\mathcal{A}_q = \langle Q, \Sigma, q, \delta_0, \delta_1 \rangle .$$

We have the following lemma:

**Lemma 2.** *Given a closed  $\lambda$ -term  $M$  of type 0:  $BT(M) \in L(\mathcal{A}_q)$  iff  $q \leq \llbracket M \rrbracket$ .*

*Proof.* We start by showing that if  $\mathcal{A}_q$  accepts  $BT(M)$  then  $q \leq \llbracket M \rrbracket$ . Proposition 1 reduces this implication to proving that  $q \leq \llbracket BT(M) \rrbracket$ . Since  $\llbracket BT(M) \rrbracket = \bigwedge \{ \llbracket BT(M) \downarrow_k \rrbracket \mid k \in \mathbb{N} \}$ , we need to show that for every  $k > 0$ ,  $q \leq \llbracket BT(M) \downarrow_k \rrbracket$ . Fix an accepting run  $r$  of  $\mathcal{A}_q$  on  $BT(M)$ . We are going to show that for every  $v$  in the domain of  $BT(M) \downarrow_k$ ,  $r(v) \leq \llbracket M_v^k \rrbracket$ . This will imply that  $r(\varepsilon) = q \leq \llbracket BT(M) \rrbracket \downarrow_k$ .

We proceed by induction on the height of  $v$ . In case  $v$  is a ‘‘cut leaf’’ (or a ‘‘non-converging’’ leaf) then  $M_v^k$  is  $\omega^0$  (or  $\Omega^0$ ) and  $\llbracket M_v^k \rrbracket$  is the greatest element of  $\mathcal{S}_0$  so that  $r(v)$  is indeed smaller than  $\llbracket M_v^k \rrbracket$ . In case  $v$  is a ‘‘normal leaf’’ then  $M_v^k$  is a constant  $c$  of type 0. Since  $r$  is an accepting run, we need to have, by definition,  $r(v) \leq \rho(c) = \llbracket M_v^k \rrbracket$ . In case  $v$  is an internal node then  $M_v^k = aM_{v1}^k M_{v2}^k$ , and, by induction, we have that  $r(vi) \leq \llbracket M_{vi}^k \rrbracket$ . Moreover, because  $r$  is a run, we need to have  $r(v) \leq \rho(a)(r(v1))(r(v2))$ , but since  $\rho(a)$  is monotone, and  $r(vi) \leq \llbracket M_{vi}^k \rrbracket$ , we have  $\rho(a)(r(v1))(r(v2)) \leq \rho(a)(\llbracket M_{v1}^k \rrbracket)(\llbracket M_{v2}^k \rrbracket) = \llbracket M_v^k \rrbracket$ . This proves, as expected, that  $r(v) \leq \llbracket M_v^k \rrbracket$ .

Now given  $q \leq \llbracket M \rrbracket$  we are going to construct a run of  $\mathcal{A}_q$  on  $BT(M)$ . Recall that for a node  $v$  of  $BT(M)$  we use  $M_v$  to denote the subtree rooted in this node. Take  $r$  defined by  $r(v) = \llbracket M_v \rrbracket$  for every  $v$ . We show that  $r$  is a run of the automaton  $\mathcal{A}_{\llbracket M \rrbracket}$ . Since  $q \leq \llbracket M \rrbracket$ , by the definitions of  $\delta_0$  and  $\delta_1$ , this run can be easily turned into a run of  $\mathcal{A}_q$ .

By definition  $r(\varepsilon) = \llbracket M \rrbracket = \llbracket BT(M) \rrbracket$ . In case  $v$  is a leaf  $c$ , then  $r(v) = \rho(c)$  and we have  $\delta_0(c, \rho(c)) = tt$ . In case  $v$  is an internal node labeled by  $a$ , then, by definition  $\llbracket M_v \rrbracket = \rho(a)(\llbracket M_{v1} \rrbracket, \llbracket M_{v2} \rrbracket)$ , so  $(\llbracket M_{v1} \rrbracket, \llbracket M_{v2} \rrbracket)$  is in  $\delta_1(a, \llbracket M_v \rrbracket)$ .

This lemma and Proposition 2 allow us to infer the announced correspondence.

**Theorem 1.** *A language  $L$  of  $\lambda$ -terms is recognized by a GFP-model iff it is a boolean combination of languages of  $\Omega$ -blind TAC automata.*

*Proof.* For the left to right direction take a model  $\mathcal{S}$  and  $p \in \mathcal{S}_0$ . By the above lemma we get that the language recognized by  $\{p\}$  is

$$L_p = L(\mathcal{A}_p) - \bigcup \{ L(\mathcal{A}_q) \mid q \in \mathcal{S}_0 \wedge q \neq p \wedge q \leq p \}$$

So given  $F$  included in  $\mathcal{S}_0$ , the language recognized by  $F$  is  $\bigcup_{p \in F} L_p$ .

For the other direction we take an automaton for every basic language in a boolean combination. We make a product of the corresponding GFP models given by Proposition 2, and take the appropriate  $F$  defined by the form of the boolean combination of the basic languages.

Using the results in [SMGB12], it can be shown that typings in Kobayashi’s type systems [Kob09b] give precisely values in GFP models.

## 4 A model for insightful TAC automata

The goal of this section is to present a model capable of recognizing languages of insightful TAC automata. Theorem 1 implies that the fixpoint operator in such a model can be neither the greatest nor the least fixpoint. In the first subsection we will construct a model containing at the same time a model with the least fixpoint and a model with the greatest fixpoint. We cannot just take the model generated by the product of the base sets of the two models as we will need that the value of a term in the least fixpoint component influences the value in the greatest fixpoint component. In the second part of this section we will show how to interpret insightful TAC automata in such a model.

### 4.1 Model construction and basic properties

In this section we build a model  $\mathcal{K}$  intended to recognize the language of a given insightful TAC automaton. This model is built on top of the standard model  $\mathcal{D}$  for detecting if a term has a head-normal form.

Consider a family of sets  $\{\mathcal{D}_\alpha\}_{\alpha \in \mathcal{T}}$ ; where  $\mathcal{D}_0 = \{\perp, \top\}$  is the two element lattice, and  $\mathcal{D}_{\alpha \rightarrow \beta}$  is the set of monotone functions from  $\mathcal{D}_\alpha$  to  $\mathcal{D}_\beta$ . So for every  $\alpha$ ,  $\mathcal{D}_\alpha$  is a finite lattice. We shall refer to the minimal and maximal element of  $\mathcal{D}_\alpha$  respectively with the notations  $\perp_\alpha$  and  $\top_\alpha$ .

Consider the model  $\mathcal{D} = \langle \{\mathcal{D}_\alpha\}_{\alpha \in \mathcal{T}}, \rho \rangle$  where  $\omega$  and  $\Omega$  are interpreted as the least elements, and  $Y$  is interpreted as the least fixpoint operator. So  $\mathcal{D}$  is a dual of a GFP model as presented in Definition 2. The reason for not taking a GFP model here is that we would prefer to use the greatest fixpoint later in the construction. To all constants other than  $Y$ ,  $\omega$ , and  $\Omega$  the interpretation  $\rho$  assigns the greatest element of the appropriate type. The following theorem is well-known (cf [AC98] page 130).

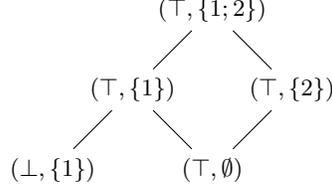
**Theorem 2.** *For every closed term  $M$  of type 0 without  $\omega$  we have:*

$$BT(M) = \Omega \quad \text{iff} \quad \llbracket M \rrbracket_{\mathcal{D}} = \perp.$$

We fix a finite set  $Q$  and its subset  $Q_\Omega \subseteq Q$ . Later these will be the set of states of a TAC automaton, and the set of states from which this automaton accepts  $\Omega$ , respectively. To capture the power of such an automaton, we are going to define a model  $\mathcal{K}(Q, Q_\Omega)$  of the  $\lambda Y$ -calculus based on an applicative structure  $\mathcal{K}_{Q, Q_\Omega} = (\mathcal{K}_\alpha)_{\alpha \in \mathcal{T}}$  and with a non-standard interpretation of the fixpoint. Roughly, this model will live inside the product of  $\mathcal{D}$  and the GFP model  $\mathcal{S}$  for an  $\Omega$ -blind automaton. The idea is that  $\mathcal{K}(Q, Q_\Omega)$  will have a projection on  $\mathcal{D}$  but not necessarily on  $\mathcal{S}$ . This allows the model to observe whether a term converges or not, and at the same time to use this information in computing in the second component.

**Definition 5.** *For a given finite set  $Q$  and  $Q_\Omega \subseteq Q$  we define a family of sets  $\mathcal{K}_{Q, Q_\Omega} = (\mathcal{K}_\alpha)_{\alpha \in \mathcal{T}}$  that is defined by mutual recursion together with a relation  $\mathcal{L} = (\mathcal{L}_\alpha)_{\alpha \in \mathcal{T}}$  such that  $\mathcal{L}_\alpha \subseteq \mathcal{K}_\alpha \times \mathcal{D}_\alpha$ :*

1. we let  $\mathcal{K}_0 = \{(\top, P) \mid P \subseteq Q\} \cup \{(\perp, Q_\Omega)\}$  with the order:  $(d_1, P_1) \leq (d_2, P_2)$  iff  $d_1 \leq d_2$  in  $\mathcal{D}_0$  and  $P_1 \subseteq P_2$ . (cf. Figure 1)
2.  $\mathcal{L}_0 = \{((d, P), d) \mid (d, P) \in \mathcal{K}_0\}$ ,
3.  $\mathcal{K}_{\alpha \rightarrow \beta} = \{f \in \text{mon}[\mathcal{K}_\alpha \rightarrow \mathcal{K}_\beta] \mid \exists d \in \mathcal{D}_{\alpha \rightarrow \beta}. \forall (g, e) \in \mathcal{L}_\alpha. (f(g), d(e)) \in \mathcal{L}_\beta\}$ ,
4.  $\mathcal{L}_{\alpha \rightarrow \beta} = \{(f, d) \in \mathcal{K}_{\alpha \rightarrow \beta} \times \mathcal{D}_{\alpha \rightarrow \beta} \mid \forall (g, e) \in \mathcal{L}_\alpha. (f(g), d(e)) \in \mathcal{L}_\beta\}$ .



**Fig. 1.** The order  $\mathcal{K}_0$  for  $Q = \{1, 2\}$  and  $Q_\Omega = \{1\}$

Note that every  $\mathcal{K}_\alpha$  is finite since it lives inside the standard model constructed from  $\mathcal{D}_0 \times \mathcal{P}(Q)$  as the base set. Moreover, as we shall see later, for every  $\alpha$ ,  $\mathcal{K}_\alpha$  is a join semilattice and thus has a greatest element. Recall that a TAC automaton is supposed to accept unsolvable terms from states  $Q_\Omega$ . So the unsolvable terms of type 0 should have  $Q_\Omega$  as a part of their meaning. This is why  $\perp$  of  $\mathcal{D}_0$  is associated to  $(\perp, Q_\Omega)$  in  $\mathcal{K}_0$  via the relation  $\mathcal{L}_0$ . This also explains why we needed to take the least fixpoint in  $\mathcal{D}$ . If we had taken the greatest fixpoint then the unsolvable terms would have evaluated to  $\top$  and the solvable ones to  $\perp$ . In consequence we would have needed to relate  $\top$  with  $(\top, Q_\Omega)$ , and we would have been forced to relate  $\perp$  with  $(\perp, Q)$ . But then  $(\top, Q_\Omega)$  and  $(\perp, Q)$  are incomparable in  $\mathcal{K}_0$ , and this makes it impossible to construct an order preserving injection from  $\mathcal{D}_0$  to  $\mathcal{K}_0$ .

The following lemma shows that for every type  $\alpha$ ,  $\mathcal{K}_\alpha$  is a join semilattice.

**Lemma 3.** *Given  $(f_1, d_1)$  and  $(f_2, d_2)$  in  $\mathcal{L}_\alpha$ , then  $f_1 \vee f_2$  is in  $\mathcal{K}_\alpha$  and  $(f_1 \vee f_2, d_1 \vee d_2)$  is in  $\mathcal{L}_\alpha$ .*

*Proof.* We proceed by induction on the structure of the type. For the base type the lemma is immediate from the definition. For the induction step consider a type of a form  $\alpha \rightarrow \beta$  and two functions  $f_1$  and  $f_2$  in  $\text{mon}[\mathcal{K}_\alpha \rightarrow \mathcal{K}_\beta]$ . Since, by induction,  $\mathcal{K}_\beta$  is a join semilattice, we have that  $f_1 \vee f_2$  is also in  $\text{mon}[\mathcal{K}_\alpha \rightarrow \mathcal{K}_\beta]$ . By assumption of the lemma, for every  $(p, e)$  in  $\mathcal{L}_\alpha$  we have that  $(f_1(p), d_1(e))$  and  $(f_2(p), d_2(e))$  are in  $\mathcal{L}_\beta$ . The induction hypothesis implies that  $(f_1(p) \vee f_2(p), d_1(e) \vee d_2(e))$  is in  $\mathcal{L}_\beta$ . As by induction hypothesis  $\mathcal{K}_\beta$  is a join semilattice, we get  $(f_1 \vee f_2)(p) = f_1(p) \vee f_2(p)$  is in  $\mathcal{K}_\beta$ . Thus  $((f_1 \vee f_2)(p), (d_1 \vee d_2)(e))$  is in  $\mathcal{L}_\beta$ . Since  $(p, e) \in \mathcal{L}_\alpha$  was arbitrary this implies that  $f_1 \vee f_2$  is in  $\mathcal{K}_{\alpha \rightarrow \beta}$  and  $(f_1 \vee f_2, d_1 \vee d_2)$  is in  $\mathcal{L}_{\alpha \rightarrow \beta}$ .

A consequence of this lemma and of the finiteness of  $\mathcal{K}_\alpha$  is that  $\mathcal{K}_\alpha$  has a greatest element that we denote  $\top_\alpha$ . The lemma also implies the existence of certain meets.

**Corollary 1.** *For every type  $\alpha$  and  $f_1, f_2$  in  $\mathcal{K}_\alpha$ . If there is  $g \in \mathcal{K}_\alpha$  such that  $g \leq f_1$  and  $g \leq f_2$  then  $f_1$  and  $f_2$  have a greatest lower bound  $f_1 \wedge f_2$ . Moreover if  $(f_1, d_1)$  and  $(f_2, d_2)$  are in  $\mathcal{L}_\alpha$  then  $(f_1 \wedge f_2, d_1 \wedge d_2)$  is in  $\mathcal{L}_\alpha$ .*

*Proof.* Just take  $f_1 \wedge f_2 = \bigvee \{g \in \mathcal{K}_\alpha \mid g \leq f_1 \text{ and } g \leq f_2\}$ . As  $\mathcal{K}_\alpha$  is finite element, the set  $\{g \in \mathcal{K}_\alpha \mid g \leq f_1 \text{ and } g \leq f_2\}$  is finite. Thus, an iterative use of Lemma 3 shows that  $f_1 \wedge f_2$  exists. It is then straightforward to see that  $f_1 \wedge f_2$  is indeed the greatest lower bound.

Now as  $\mathcal{D}_\alpha$  is a complete lattice, we also

We are now going to show that every constant function of  $\text{mon}[\mathcal{K}_\alpha \rightarrow \mathcal{K}_\beta]$  is actually in  $\mathcal{K}_{\alpha \rightarrow \beta}$ .

**Lemma 4.** *For every  $q$  in  $\mathcal{K}_\beta$ , the function  $c_q$  of  $\text{mon}[\mathcal{K}_\alpha \rightarrow \mathcal{K}_\beta]$  such that for every  $p$  in  $\mathcal{K}_\alpha$ ,  $c_q(p) = q$  is in  $\mathcal{K}_{\alpha \rightarrow \beta}$ .*

*Proof.* To show that  $c_q$  is in  $\mathcal{K}_{\alpha \rightarrow \beta}$ , we need to find  $h_q$  in  $\mathcal{D}_{\alpha \rightarrow \beta}$  such that for every  $(p, e)$ ,  $(c_q(p), h_q(e))$  is in  $\mathcal{L}_\beta$ . Since  $q$  is in  $\mathcal{K}_\beta$ , there is  $d$  such that  $(q, d)$  is in  $\mathcal{L}_\beta$ . It suffices to take  $h_q$  to be the function of  $\mathcal{D}_{\alpha \rightarrow \beta}$  such that for every  $e$  in  $\mathcal{D}_\alpha$ ,  $h_q(e) = d$ .

As one easily observes that for every  $p \in \mathcal{K}_\alpha$ ,  $\top_{\alpha \rightarrow \beta}(p) = \top_\beta$ , a consequence of this lemma is that  $(\top_\alpha, \top_\alpha)$  is in  $\mathcal{L}_\alpha$  for every  $\alpha$ .

This lemma allows us to define inductively on types the family of constant functions  $(\perp_\alpha)_{\alpha \in \mathcal{T}}$  as follows:

1.  $\perp_0 = (\perp, Q_\Omega)$ ,
2.  $\perp_{\alpha \rightarrow \beta}(h) = \perp_\beta$  for every  $h$  in  $\mathcal{K}_\alpha$ .

Notice that  $\perp_\alpha$  is a minimal element of  $\mathcal{K}_\alpha$ , but that  $\mathcal{K}_\alpha$  does not have a least element in general.

For every  $d$  in  $\mathcal{D}_\alpha$ , we denote by  $L_d$  the set of elements of  $\mathcal{K}_\alpha$  that are related to it:

$$L_d = \{p \in \mathcal{K}_\alpha \mid (p, d) \in \mathcal{L}_\alpha\}.$$

**Definition 6.** *A type  $\alpha$  is  $\mathcal{D}$ -complete if, for every  $d$  in  $\mathcal{D}_\alpha$ :*

1.  $L_d$  is not empty,
2.  $\perp_\alpha \leq \bigvee L_d$ ,
3. for every  $(f, e)$  in  $\mathcal{L}_\alpha$ :  $f \leq \bigvee L_d$  iff  $e \leq d$ .

Later we will show that every type is  $\mathcal{D}$ -complete, but for this we will need some preparatory lemmas.

**Lemma 5.** *If  $\alpha$  is a  $\mathcal{D}$ -complete type and  $d$  is in  $\mathcal{D}_\alpha$  then  $(\bigvee L_d, d)$  is in  $\mathcal{L}_\alpha$ .*

*Proof.* Since  $\alpha$  is  $\mathcal{D}$ -complete,  $L_d$  is not empty, and the conclusion follows directly from Lemma 3.

**Lemma 6.** *If  $\alpha$  is a  $\mathcal{D}$ -complete type, and  $d, e \in \mathcal{D}_\alpha$  then:  $e \leq d$  iff  $\bigvee L_e \leq \bigvee L_d$ .*

*Proof.* As  $\alpha$  is  $\mathcal{D}$ -complete both  $L_e$  and  $L_d$  are not empty and therefore,  $\bigvee L_e$  and  $\bigvee L_d$  are well-defined. Lemma 5 also gives that  $(\bigvee L_e, e)$  is in  $\mathcal{L}_\alpha$ . Now from  $\mathcal{D}$ -completeness of  $\alpha$ , we have that  $\bigvee L_e \leq \bigvee L_d$  iff  $e \leq d$ .

We now define an operation  $(\cdot)^\uparrow$  that, as we will show later, is an embedding for  $\mathcal{D}$  into  $\mathcal{K}$ . But for this we need the notion of *co-step functions*: given two partial orders  $L_1$  and  $L_2$  where  $L_2$  has a greatest element  $\top$ ,  $p$  in  $L_1$  and  $q$  in  $L_2$ , we write  $p \nearrow q$  for the function of  $\text{mon}[L_1 \rightarrow L_2]$  such that for  $r$  in  $L_1$ ,

$$(p \nearrow q)(r) = \begin{cases} q & \text{when } r \leq p \\ \top & \end{cases}$$

**Definition 7.** Let  $\alpha, \beta$  be  $\mathcal{D}$ -complete types. For every  $h \in \mathcal{D}_{\alpha \rightarrow \beta}$  and every  $d \in \mathcal{D}_\alpha$  we define two monotone functions and the element  $h^\uparrow$ :

$$\begin{aligned} f_{h,d} &= \bigvee L_d \nearrow \bigvee L_{h(d)}, & \bar{f}_{h,d} &= d \nearrow h(d), \\ h^\uparrow &= \bigwedge_{d \in \mathcal{D}} f_{h,d}. \end{aligned}$$

For  $h$  in  $\mathcal{D}_0$ , we define  $h^\uparrow$  to be  $(\perp, Q_\Omega)$  when  $h = \perp$ , and to be  $(\top, Q)$  when  $h = \top$ .

The next lemma summarizes all essential properties of the model  $\mathcal{K}$ .

**Lemma 7.** For all  $\mathcal{D}$ -complete types  $\alpha, \beta$ , for every  $h \in \mathcal{D}_{\alpha \rightarrow \beta}$  and every  $d \in \mathcal{D}_\alpha$ :

1.  $(f_{h,d}, \bar{f}_{h,d})$  is in  $\mathcal{L}_{\alpha \rightarrow \beta}$ ;
2.  $\perp_{\alpha \rightarrow \beta} \leq f_{h,d}$ ;
3.  $h^\uparrow$  is an element of  $\mathcal{K}_{\alpha \rightarrow \beta}$  and  $(h^\uparrow, h) \in \mathcal{L}_{\alpha \rightarrow \beta}$ ;
4. if  $(p, e) \in \mathcal{L}_\alpha$  then  $h^\uparrow(p) = \bigvee L_{h(e)}$ ;
5.  $h^\uparrow = \bigvee L_h$ .

*Proof.* For the first item we take  $(p, e) \in \mathcal{L}_\alpha$ , and show that  $(f_{h,d}(p), \bar{f}_{h,d}(e)) \in \mathcal{L}_\beta$ . This will be sufficient by the definition of  $\mathcal{L}_{\alpha \rightarrow \beta}$ . Lemma 5 gives  $(\bigvee L_d, d) \in \mathcal{L}_\alpha$  and  $(\bigvee L_{h(d)}, h(d)) \in \mathcal{L}_\beta$ . By  $\mathcal{D}$ -completeness of  $\alpha$ :  $p \leq \bigvee L_d$  iff  $e \leq d$ . We have two cases. If  $p \leq \bigvee L_d$  then  $f_{h,d}(p) = \bigvee L_{h(d)}$  and  $\bar{f}_{h,d}(e) = h(d)$ . Otherwise,  $p \not\leq \bigvee L_d$  that gives  $f_{h,d}(p) = \top_\beta$  and  $\bar{f}_{h,d}(e) = \top_\beta$ . With the help of Lemma 5 in both cases we have that the result is in  $\mathcal{L}_\beta$ , and we are done.

For the second item, by  $\mathcal{D}$ -completeness of  $\beta$  we have  $\bigvee L_{h(d)} \geq \perp_\beta$ . In the proof of the first item we have seen that  $f_{h,d}(p) \geq \bigvee L_{h(d)}$  for every  $p \in \mathcal{K}_\alpha$ . Since  $\perp_{\alpha \rightarrow \beta}(p) = \perp_\beta$  we get  $\perp_{\alpha \rightarrow \beta} \leq f_{h,d}$ .

In order to show the third item we use the first item telling us that  $(f_{h,e}, \bar{f}_{h,e})$  is in  $\mathcal{L}_{\alpha \rightarrow \beta}$  for every  $e \in \mathcal{D}_\alpha$ . Since by the second item  $\perp_\alpha \leq f_{h,e}$ , Corollary 1 shows that  $(\bigwedge_{e \in \mathcal{D}_\alpha} f_{h,e}, \bigwedge_{e \in \mathcal{D}_\alpha} \bar{f}_{h,e})$  is in  $\mathcal{L}_{\alpha \rightarrow \beta}$ . Directly from the definition of co-step functions we have  $\bigwedge_{e \in \mathcal{D}_\alpha} e \nearrow h(e) = h$ . This gives, as desired,  $(\bigwedge_{e \in \mathcal{D}_\alpha} f_{h,e}, h)$  in  $\mathcal{L}_{\alpha \rightarrow \beta}$ .

For the fourth item, take an arbitrary  $(p, e) \in \mathcal{L}_\alpha$ . We show that  $h^\uparrow(p) = \bigvee L_{d(e)}$ . By definition  $h^\uparrow(p) = \bigwedge_{e' \in \mathcal{D}_\alpha} f_{h, e'}(p)$ . Moreover  $f_{h, e'}(p) = \bigvee L_{h(e')}$  if  $p \leq \bigvee L_{e'}$ , and  $f_{h, e'}(p) = \top_\beta$  otherwise. By  $\mathcal{D}$ -completeness of  $\alpha$ :  $p \leq \bigvee L_{e'}$  iff  $e \leq e'$ . So  $h^\uparrow(p) = \bigwedge_{e' \in \mathcal{D}_\alpha} f_{h, e'}(p) = \bigwedge \{\bigvee L_{h(e')} : e \leq e'\}$ . By Lemma 6, if  $e \leq e'$  then  $\bigvee L_{h(e)} \leq \bigvee L_{h(e')}$ . Hence  $h^\uparrow(p) = \bigvee L_{h(e)}$ .

For the last item we want to show that  $h^\uparrow = \bigvee L_h$ . We know that  $h^\uparrow \in L_h = \{g \in \mathcal{K}_{\alpha \rightarrow \beta} : (g, h) \in \mathcal{L}_\alpha\}$  since  $(h^\uparrow, h) \in \mathcal{L}_{\alpha \rightarrow \beta}$  by the third item. We show that for every  $g \in L_h$ ,  $g \leq h^\uparrow$ . Take some  $(p, e) \in \mathcal{L}_\alpha$ . We have  $(g(p), h(e)) \in \mathcal{L}_\beta$ , hence  $g(p) \leq \bigvee L_{h(e)}$  by definition of  $L_{h(e)}$ . Since  $h^\uparrow(p) = \bigvee L_{h(e)}$  by the fourth item, we get  $g \leq h^\uparrow$ .

**Lemma 8.** *Every type  $\alpha$  is  $\mathcal{D}$ -complete.*

*Proof.* This is proved by induction on the structure of the type. The case of the base type follows by direct examination. For the induction step consider a type  $\alpha \rightarrow \beta$  and suppose that  $\alpha$  and  $\beta$  are  $\mathcal{D}$ -complete. Given  $d$  in  $\mathcal{D}_{\alpha \rightarrow \beta}$ , Lemma 7 gives that  $(d^\uparrow, d)$  is in  $\mathcal{L}_{\alpha \rightarrow \beta}$  proving that  $L_d \neq \emptyset$ , it also gives that  $\perp_{\alpha \rightarrow \beta} \leq d^\uparrow$  and  $d^\uparrow = \bigvee L_d$  so that we obtain  $\perp_{\alpha \rightarrow \beta} \leq \bigvee L_d$ . It just remains to prove that given  $(f, e)$  in  $\mathcal{L}_{\alpha \rightarrow \beta}$ ,  $f \leq \bigvee L_d$  iff  $e \leq d$ .

We first remark that, as by induction hypothesis,  $\alpha$  and  $\beta$  are  $\mathcal{D}$ -complete, by Lemma 7 (items (4) and (5)), for every  $(p, e') \in \mathcal{L}_\alpha$  we have:

$$\bigvee L_{d(e')} = d^\uparrow(p) = \left( \bigvee L_d \right) (p) \quad (1)$$

Let's first suppose that  $e \leq d$ . Take a  $p \in \mathcal{K}_\alpha$ . By definition of the model there is  $e'$ , such that  $(p, e') \in \mathcal{L}_\alpha$ . As  $\alpha$  is  $\mathcal{D}$ -complete, Lemma 6 gives us  $\bigvee L_{e(e')} \leq \bigvee L_{d(e')}$ . By definition of  $\mathcal{L}_{\alpha \rightarrow \beta}$  we have that  $(f(p), e(e')) \in \mathcal{L}_\beta$ , so  $f(p) \leq \bigvee L_{e(e')}$  by definition of  $L_{e(e')}$ . This gives  $f(p) \leq \bigvee L_{e(e')} \leq \bigvee L_{d(e')}$ . Finally Equation (1) shows the desired  $f(p) \leq \left( \bigvee L_d \right) (p)$  for every  $p \in \mathcal{K}_\alpha$ .

Let us now suppose that  $f \leq \bigvee L_d$ . The  $\mathcal{D}$ -completeness of  $\alpha$  tells us that for every  $e'$  in  $\mathcal{D}_\alpha$  there is  $p$  in  $\mathcal{K}_\alpha$  so that  $(p, e')$  is in  $\mathcal{L}_\alpha$ . Then Equation (1) gives  $f(p) \leq \left( \bigvee L_d \right) (p) = \bigvee L_{d(e')}$ . Now, as by induction  $\beta$  is  $\mathcal{D}$ -complete, the fact that  $(f(p), e(e')) \in \mathcal{L}_\beta$  entails  $e(e') \leq d(e')$ . As  $e'$  was arbitrary we obtain that  $e \leq d$ .

The proposition below sums up the properties of the embedding  $(\cdot)^\uparrow$  from Definition 7.

**Proposition 3.** *Given a type  $\alpha$ , and  $d$  in  $\mathcal{D}_\alpha$ , the element  $d^\uparrow$  from  $\mathcal{K}_\alpha$  is such that:*

1.  $(d^\uparrow, d)$  is in  $\mathcal{L}_\alpha$ ,
2. if  $e \in \mathcal{D}_\alpha$  and  $d \leq e$  then  $d^\uparrow \leq e^\uparrow$ ,
3. if  $(f, d)$  is in  $\mathcal{L}_\alpha$ , then  $f \leq d^\uparrow$ ,
4. if  $\alpha = \alpha_1 \rightarrow \alpha_2$  and  $(g, e)$  is in  $\mathcal{L}_{\alpha_1}$  then  $d^\uparrow(g) = (d(e))^\uparrow$

*Proof.* These properties follow directly from Lemma 7, except for the second property for which a small calculation is needed. Since  $(d^\uparrow, d)$  is in  $\mathcal{L}_\alpha$  and  $d \leq e$  then by Lemma 7:  $d^\uparrow \leq \bigvee L_e$ . The latter is precisely  $e^\uparrow$  by Lemma 7.

In particular, in combination with Lemma 7 item 3., this proposition shows that the operator  $(\cdot)^\dagger$  commutes with the application—that is  $d^\dagger(e^\dagger) = (d(e))^\dagger$ .

The next lemma shows that the relation  $\mathcal{L}_\alpha$  is functional.

**Lemma 9.** *For every type  $\alpha$  and  $f$  in  $\mathcal{K}_\alpha$ : if  $(f, d_1)$  and  $(f, d_2)$  are in  $\mathcal{L}_\alpha$ , then  $d_1 = d_2$ .*

*Proof.* We proceed by induction on the structure of the type. The case of the base type follows from a direct inspection. For the induction step suppose that both  $(f, d_1)$  and  $(f, d_2)$  are in  $\mathcal{L}_{\alpha \rightarrow \beta}$ . Take an arbitrary  $e \in \mathcal{D}_\alpha$ . By Lemma 7 we have  $(e^\dagger, e) \in \mathcal{L}_\alpha$ . Therefore  $(f(e^\dagger), d_1(e))$  and  $(f(e^\dagger), d_2(e))$  in  $\mathcal{L}_\beta$ . The induction hypothesis implies that  $d_1(e) = d_2(e)$ . Since  $e$  was arbitrary we get  $d_1 = d_2$ .

Since, by definition, for every  $f \in \mathcal{K}_\alpha$  we have  $(f, d) \in \mathcal{L}_\alpha$  for some  $d \in \mathcal{D}_\alpha$ , the above lemma gives us a projection of  $\mathcal{K}_\alpha$  to  $\mathcal{D}_\alpha$ .

**Definition 8.** *For every type  $\alpha$  and  $f \in \mathcal{K}_\alpha$  we let  $\bar{f}$  to be the unique element of  $\mathcal{D}_\alpha$  such that  $(f, \bar{f}) \in \mathcal{L}_\alpha$ .*

Notice that as, from Proposition 3, for every  $d$  in  $\mathcal{D}_\alpha$ ,  $(d^\dagger, d)$  is in  $\mathcal{L}_\alpha$ , we have that  $\bar{d^\dagger} = d$ .

We immediately state some properties of the projection. We start by showing that it commutes with the application.

**Lemma 10.** *Given  $f$  in  $\mathcal{K}_{\alpha \rightarrow \beta}$  and  $p$  in  $\mathcal{K}_\alpha$ ,  $\overline{f(p)} = \bar{f}(\bar{p})$ .*

*Proof.* We have  $(f, \bar{f})$  in  $\mathcal{L}_{\alpha \rightarrow \beta}$  and  $(p, \bar{p})$  in  $\mathcal{L}_\alpha$ , so that  $(f(p), \bar{f}(\bar{p}))$  is in  $\mathcal{L}_\beta$  and thus  $\overline{f(p)} = \bar{f}(\bar{p})$ .

**Lemma 11.** *Given  $f$  and  $g$  in  $\mathcal{K}_\alpha$ , if  $f \leq g$  then  $\bar{f} \leq \bar{g}$ .*

*Proof.* We proceed by induction on the structure of the types. The case of the base type follows by a straightforward inspection. For the induction step take  $f \leq g$  in  $\mathcal{K}_{\alpha \rightarrow \beta}$ . For an arbitrary  $d \in \mathcal{D}_\alpha$  we have  $f(d^\dagger) \leq g(d^\dagger)$ . By induction hypothesis on type  $\beta$  we get  $\overline{f(d^\dagger)} \leq \overline{g(d^\dagger)}$ . By Lemma 10 we obtain  $\overline{f(d^\dagger)} = \bar{f}(\bar{d^\dagger}) = \bar{f}(d)$ . The last equality follows from the fact that  $\bar{d^\dagger} = d$  since  $(d^\dagger, d)$  is in  $\mathcal{L}_\alpha$  by Proposition 3. Of course the same equalities hold for  $g$  too. So  $\bar{f}(d) \leq \bar{g}(d)$  for arbitrary  $d$ , and we are done.

Taking an abstract view on the operations  $(\cdot)^\dagger$  and  $\bar{(\cdot)}$ , all the properties we have shown prove that:

1.  $(\cdot)^\dagger$  is a functor from  $\mathcal{D}$  to  $\mathcal{K}$ ,
2.  $\bar{(\cdot)}$  is a functor from  $\mathcal{K}$  to  $\mathcal{D}$ ,
3. at every type both mappings are monotonous and moreover they form a Galois connection in the sense that  $\bar{f} \leq d$  iff  $f \leq d^\dagger$ ,
4. and  $\bar{(\cdot)}, (\cdot)^\dagger$  forms a retraction:  $\bar{d^\dagger} = d$ .

We are now going to give the definition of the interpretation of the fixpoint combinator in  $\mathcal{K}$ . This definition is based on that of the fixpoint operator in  $\mathcal{D}$ . As a shorthand, we write  $\text{fix}_\alpha$  for the operation in  $\mathcal{D}_{(\alpha \rightarrow \alpha) \rightarrow \alpha}$  that maps a function of  $\mathcal{D}_{\alpha \rightarrow \alpha}$  to its least fixpoint.

**Lemma 12.** *Given  $f$  in  $\mathcal{K}_{\alpha \rightarrow \alpha}$ , we have  $f(\text{fix}_\alpha(\bar{f})^\dagger) \leq \text{fix}_\alpha(\bar{f})^\dagger$ .*

*Proof.* By Proposition 3, we have that  $(\text{fix}_\alpha(\bar{f})^\dagger, \text{fix}_\alpha(\bar{f}))$  is in  $\mathcal{L}_\alpha$ . Moreover,  $(f, \bar{f})$  is in  $\mathcal{L}_{\alpha \rightarrow \alpha}$ , therefore, by definition of  $\mathcal{L}_{\alpha \rightarrow \alpha}$ , we have  $(f(\text{fix}_\alpha(\bar{f})^\dagger), \bar{f}(\text{fix}_\alpha(\bar{f}))^\dagger) = (f(\text{fix}_\alpha(\bar{f})^\dagger), \text{fix}_\alpha(\bar{f}))$  is in  $\mathcal{L}_\alpha$ . Then by Proposition 3 we have  $f(\text{fix}_\alpha(\bar{f})^\dagger) \leq \text{fix}_\alpha(\bar{f})^\dagger$ .

The above lemma guarantees that the sequence  $f^n(\text{fix}_\alpha(\bar{f})^\dagger)$  is decreasing. We can now define an operator that, as we will show, is the fixpoint operator we are looking for.

**Definition 9.** *For every type  $\alpha$  and  $f \in \mathcal{K}_\alpha$  define*

$$\text{Fix}_\alpha(f) = \bigwedge_{n \in \mathbb{N}} (f^n(\text{fix}_\alpha(\bar{f})^\dagger))$$

We show that  $\text{Fix}_\alpha$  is monotone.

**Lemma 13.** *Given  $f$  and  $g$  in  $\mathcal{K}_{\alpha \rightarrow \alpha}$ , if  $f \leq g$  then  $\text{Fix}_\alpha(f) \leq \text{Fix}_\alpha(g)$ .*

*Proof.* By Lemma 11,  $f \leq g$  implies  $\bar{f} \leq \bar{g}$ , as  $\text{fix}_\alpha$  is monotone, we have  $\text{fix}_\alpha(\bar{f}) \leq \text{fix}_\alpha(\bar{g})$  and  $\text{fix}_\alpha(\bar{f})^\dagger \leq \text{fix}_\alpha(\bar{g})^\dagger$  by Proposition 3. As  $f \leq g$  we have  $f^k(\text{fix}_\alpha(\bar{f})^\dagger) \leq g^k(\text{fix}_\alpha(\bar{g})^\dagger)$  for every  $k$  in  $\mathbb{N}$ . Therefore  $\bigwedge_{n \in \mathbb{N}} f^n(\text{fix}_\alpha(\bar{f})^\dagger) \leq \bigwedge_{n \in \mathbb{N}} g^n(\text{fix}_\alpha(\bar{g})^\dagger)$ .

The last step is to show that  $\text{Fix}_\alpha$  is actually in  $\mathcal{K}_{(\alpha \rightarrow \alpha) \rightarrow \alpha}$ .

**Lemma 14.** *For every  $\alpha$ ,  $\text{Fix}_\alpha$  is in  $\mathcal{K}_\alpha$  and  $(\text{Fix}_\alpha, \text{fix}_\alpha)$  is in  $\mathcal{L}_{(\alpha \rightarrow \alpha) \rightarrow \alpha}$ .*

*Proof.* We know that  $(f, \bar{f})$  in  $\mathcal{L}_{\alpha \rightarrow \alpha}$ . As we have seen in the proof of Lemma 12,  $(f(\text{fix}_\alpha(\bar{f})^\dagger), \text{fix}_\alpha(\bar{f}))$  is in  $\mathcal{L}_\alpha$ . Using repeatedly the defining properties of  $\mathcal{L}_{\alpha \rightarrow \alpha}$ , we obtain that for every  $n \in \mathbb{N}$ ,  $(f^n(\text{fix}_\alpha(\bar{f})^\dagger), \text{fix}_\alpha(\bar{f}))$  is in  $\mathcal{L}_\alpha$ . But  $f^n(\text{fix}_\alpha(\bar{f})^\dagger)$  is decreasing by Lemma 12. Since  $\mathcal{K}_\alpha$  is finite, we get  $(\bigwedge_{n \in \mathbb{N}} f^n(\text{fix}_\alpha(\bar{f})^\dagger), \text{fix}_\alpha(\bar{f}))$  in  $\mathcal{L}_\alpha$ . We are done since  $\bigwedge_{n \in \mathbb{N}} f^n(\text{fix}_\alpha(\bar{f})^\dagger) = \text{Fix}_\alpha(f)$ .

We are ready to define the model we were looking for.

**Definition 10.** *For a finite set  $Q$  and its subset  $Q_\Omega \subseteq Q$  consider a tuple  $\mathcal{K}(Q, Q_\Omega, \rho) = (\{\mathcal{K}_\alpha\}_{\alpha \in \mathcal{T}}, \rho)$  where  $\{\mathcal{K}_\alpha\}_{\alpha \in \mathcal{T}}$  is as in Definition 5 and  $\rho$  is a valuation such that for every type  $\alpha$ :  $\omega^\alpha$  is interpreted as the greatest element of  $\mathcal{K}_\alpha$ ,  $Y^{(\alpha \rightarrow \alpha) \rightarrow \alpha}$  is interpreted as  $\text{Fix}_\alpha$ , and  $\Omega^\alpha$  is interpreted as  $\perp_\alpha$ .*

Notice that, according to this definition,  $\Omega^0$  is interpreted as  $(\perp, Q_\Omega)$ . So the semantics of  $\Omega$  and  $\omega$  are different in this model. Recall that  $\Omega$  is used to denote divergence, and  $\omega$  is used in the definition of truncation operation from the semantics of Böhm trees (cf. page 6).

We will show  $\mathcal{K}(Q, Q_\Omega, \rho)$  is indeed a model of  $\lambda Y$ -calculus. Since  $\mathcal{K}_{\alpha \rightarrow \beta}$  does not contain all the functions from  $\mathcal{K}_\alpha$  to  $\mathcal{K}_\beta$  we must show that there are enough of them to form a model of  $\lambda Y$ , the main problem being to show that  $\llbracket \lambda x.M \rrbracket_{\mathcal{K}}^v$  defines an element of  $\mathcal{K}$ . For this it will be more appropriate to consider the semantics of a term as a function of values of its free variables. Given a finite sequence of variables  $\mathbf{x} = x_1, \dots, x_n$  of types  $\alpha_1, \dots, \alpha_n$  respectively and a term  $M$  of type  $\beta$  with free variables in  $\mathbf{x}$ , the meaning of  $M$  in the model  $\mathcal{K}$  with respect to  $\mathbf{x}$  will be a function  $\llbracket M \rrbracket_{\mathbf{x}, \mathcal{K}}$  in  $\mathcal{K}_{\alpha_1} \rightarrow \dots \rightarrow \mathcal{K}_{\alpha_n} \rightarrow \mathcal{K}_\beta$  that represents the function  $\lambda \mathbf{p}.\llbracket M \rrbracket_{\mathcal{K}}^{[p_1/x_1, \dots, p_n/x_n]}$ . Formally it is defined as follows:

1.  $\llbracket Y^{(\beta \rightarrow \beta) \rightarrow \beta} \rrbracket_{\mathbf{x}, \mathcal{K}} = \lambda \mathbf{p}.\text{Fix}_\beta$
2.  $\llbracket a \rrbracket_{\mathbf{x}, \mathcal{K}} = \lambda \mathbf{p}.\rho(a)$
3.  $\llbracket x_i^{\alpha_i} \rrbracket_{\mathbf{x}, \mathcal{K}} = \lambda \mathbf{p}.p_i$
4.  $\llbracket \omega^\beta \rrbracket_{\mathbf{x}, \mathcal{K}} = \lambda \mathbf{p}.\top_\beta$
5.  $\llbracket \Omega^\beta \rrbracket_{\mathbf{x}, \mathcal{K}} = \lambda \mathbf{p}.\perp_\beta$
6.  $\llbracket MN \rrbracket_{\mathbf{x}, \mathcal{K}} = \lambda \mathbf{p}.\left(\llbracket M \rrbracket_{\mathbf{x}, \mathcal{K}} \mathbf{p}\right)\left(\llbracket N \rrbracket_{\mathbf{x}, \mathcal{K}} \mathbf{p}\right)$
7.  $\llbracket \lambda y.M \rrbracket_{\mathbf{x}, \mathcal{K}} = \lambda \mathbf{p}.\lambda p_y.\llbracket M \rrbracket_{\mathbf{x}y, \mathcal{K}} \mathbf{p}p_y$

Note that  $\lambda$  symbol on the right hand side of the equality is the semantic symbol used to denote a relevant function, and not a part of the syntax while the sequence  $\mathbf{p}$  denote a sequence of parameters  $p_1, \dots, p_n$  ranging respectively in  $\mathcal{K}_{\alpha_1}, \dots, \mathcal{K}_{\alpha_n}$ .

Lemma 14 ensures the existence of the meaning of  $Y$  in  $\mathcal{K}$ . With this at hand, the next lemma provides all the other facts necessary to show that the meaning of a term with respect to  $\mathbf{x}$  is always an element of the model.

**Lemma 15.** *For every sequence of types  $\boldsymbol{\alpha} = \alpha_1 \dots \alpha_n$  and every types  $\beta, \gamma$  we have the following:*

- For every constant  $p \in \mathcal{K}_\beta$  the constant function  $f_p : \alpha_1 \rightarrow \dots \rightarrow \alpha_n \rightarrow \beta$  belongs to  $\mathcal{K}$ .
- For  $i = 1, \dots, n$ , the projection  $\pi_i : \alpha_1 \rightarrow \dots \rightarrow \alpha_n \rightarrow \alpha_i$  belongs to  $\mathcal{K}$ .
- If  $f : \boldsymbol{\alpha} \rightarrow (\beta \rightarrow \gamma)$  and  $g : \boldsymbol{\alpha} \rightarrow \beta$  are in  $\mathcal{K}$  then  $\lambda \mathbf{p}.f \mathbf{p}(g \mathbf{p}) : \boldsymbol{\alpha} \rightarrow \gamma$  is in  $\mathcal{K}$ .

*Proof.* The first item of the lemma is given by Lemma 4, the second does not present more difficulty. Finally the third proceeds by a direct examination once we observe the following property of  $\mathcal{K}(Q, Q_\Omega, \rho)$ . Given two elements  $f$  of  $\text{mon}[\mathcal{K}_{\alpha_1} \rightarrow \dots \rightarrow \text{mon}[\mathcal{K}_{\alpha_n} \rightarrow \mathcal{K}_\beta]]$  and  $g$  of  $\mathcal{D}_{\alpha_1 \rightarrow \dots \rightarrow \alpha_n \rightarrow \beta}$ , if for every  $d_1, \dots, d_n$  in  $\mathcal{K}_{\alpha_1}, \dots, \mathcal{K}_{\alpha_n}$ ,  $(f(d_1, \dots, d_n), g(\bar{d}_1, \dots, \bar{d}_n)) \in \mathcal{L}_\beta$  then  $f$  is in  $\mathcal{K}_{\alpha_1 \rightarrow \dots \rightarrow \alpha_n \rightarrow \beta}$  and  $(f, g)$  is in  $\mathcal{L}_{\alpha_1 \rightarrow \dots \rightarrow \alpha_n \rightarrow \beta}$ . This observation follows directly from Proposition 3 and the definition of the model.

These observations allow us to conclude that  $\mathcal{K}(Q, Q_\Omega, \rho)$  is indeed a model of the  $\lambda Y$ -calculus, that is:

1. for every term  $M$  of type  $\alpha$  and every valuation  $\nu$  ranging of the free variables of  $M$ ,  $\llbracket M \rrbracket_{\mathcal{K}}^\nu$  is in  $\mathcal{K}_\alpha$ ,
2. given two terms  $M$  and  $N$  of type  $\alpha$ , if  $M =_{\beta\delta} N$ , then for every valuation  $\nu$ ,  $\llbracket M \rrbracket_{\mathcal{K}}^\nu = \llbracket N \rrbracket_{\mathcal{K}}^\nu$ .

**Theorem 3.** *For every finite set  $Q$  and every set  $Q_\Omega \subseteq Q$  the model  $\mathcal{K}(Q, Q_\Omega, \rho)$  as in Definition 10 is a model of the  $\lambda Y$ -calculus.*

Let us mention the following useful fact showing a correspondence between the meanings of a term in  $\mathcal{K}$  and in  $\mathcal{D}$ . The proof is immediate since  $\{\mathcal{L}_\alpha\}_{\alpha \in \mathcal{T}}$  is a logical relation (cf [AC98]).

**Lemma 16.** *For every type  $\alpha$  and closed term  $M$  of type  $\alpha$ :*

$$(\llbracket M \rrbracket_{\mathcal{K}}, \llbracket M \rrbracket_{\mathcal{D}}) \in \mathcal{L}_\alpha.$$

## 4.2 Correctness and completeness of the model

It remains to show that the model we have constructed is indeed sufficient to recognize languages of TAC automata. For the rest of the section we fix a tree signature  $\Sigma$  and a TAC automaton

$$\mathcal{A} = \langle Q, \Sigma, q^0 \in Q, \delta_1 : Q \times \Sigma_1 \rightarrow \{\text{ff}, \text{tt}\}, \delta_2 : Q \times \Sigma_2 \rightarrow \mathcal{P}(Q^2) \rangle.$$

We take a model  $\mathcal{K}$  based on  $\mathcal{K}(Q, Q_\Omega, \rho)$  as in Definition 10, where  $Q_\Omega$  is the set of states  $q$  such that  $\delta(q, \Omega) = \text{tt}$ . It remains to specify the meaning of constants like  $c : 0$  or  $a : 0^2 \rightarrow 0$  in  $\Sigma$ :

$$\begin{aligned} \rho(c) &= (\top, \{q : \delta(q, c) = \text{tt}\}) \\ \rho(a)(d_1, R_1)(d_2, R_2) &= (\top, R) \quad \text{where } d_1, d_2 \in \{\perp, \top\} \text{ and} \\ & \quad R = \{q \in Q \mid \delta(q, a) \cap R_1 \times R_2 \neq \emptyset\} \end{aligned}$$

**Lemma 17.** *For every  $a$  in  $\Sigma$  of type  $o^2 \rightarrow o$ :  $\rho(a)$  is in  $\mathcal{K}_{o^2 \rightarrow o}$  and  $(\rho(a), \top_{o^2 \rightarrow o})$  is in  $\mathcal{L}_{o^2 \rightarrow o}$ .*

*Proof.* It is easy to see that  $\rho(a)$  is monotone. For the membership in  $\mathcal{K}$  the witnessing function from  $\mathcal{D}_{o^2 \rightarrow o}$  is  $\top_{o^2 \rightarrow o}$ .

Once we know that  $\mathcal{K}$  is a model we can state some of its useful properties. The first one tells what the meaning of unsolvable terms is. The second indicates how unsolvability is taken into account in the computation of a fixpoint.

**Proposition 4.** *Given a closed term  $M$  of type  $0$ :  $BT(M) = \Omega^0$  iff  $\llbracket M \rrbracket_{\mathcal{K}} = (\perp, Q_\Omega)$ .*

*Proof.* In case  $\llbracket M \rrbracket_{\mathcal{K}} = (\perp, Q_{\Omega})$ , Lemma 16 gives us  $\llbracket M \rrbracket_{\mathcal{D}} = \perp$ . By Theorem 2 this implies  $BT(M) = \Omega^0$ .

In case  $BT(M) = \Omega^0$ , Theorem 2 entails that  $\llbracket M \rrbracket_{\mathcal{D}} = \perp$ . By Lemma 16  $(\llbracket M \rrbracket_{\mathcal{K}}, \perp)$  is in  $\mathcal{L}_0$ . But this is possible only if  $\llbracket M \rrbracket_{\mathcal{K}} = (\perp, Q_{\Omega})$ .

**Lemma 18.** *Given a type  $\beta = \beta_1 \rightarrow \dots \rightarrow \beta_l \rightarrow 0$ , a sequence of types  $\alpha = \alpha_1, \dots, \alpha_k$ , and a function  $f \in \mathcal{K}_{\alpha \rightarrow \beta \rightarrow \beta}$ , consider the functions:*

$$h = \lambda p_1 \dots p_k. \left( \overline{\text{fix}_{\alpha}(f(p_1) \dots (p_k))} \right)^{\uparrow} \quad g = \lambda e_1 \dots e_k. \text{fix}_{\beta}(\bar{f}(e_1) \dots (e_k))$$

that are respectively in  $\mathcal{K}_{\alpha_1} \rightarrow \dots \rightarrow \mathcal{K}_{\alpha_k} \rightarrow \mathcal{K}_{\beta}$  and in  $\mathcal{D}_{\alpha \rightarrow \beta}$ . Then  $h$  is in  $\mathcal{K}_{\alpha \rightarrow \beta}$  and  $(h, g)$  is in  $\mathcal{L}_{\alpha \rightarrow \beta}$ . Moreover, for every  $p_1 \in \mathcal{K}_{\alpha_1}, \dots, p_k \in \mathcal{K}_{\alpha_k}, q_1 \in \mathcal{K}_{\beta_1}, \dots, q_l \in \mathcal{K}_{\beta_l}$  we have

$$h(p_1, \dots, p_k)(q_1, \dots, q_l) = \begin{cases} (\perp, Q_{\Omega}) & \text{if } g(\bar{p}_1, \dots, \bar{p}_k)(\bar{q}_1, \dots, \bar{q}_l) = \perp \\ (\top, Q) & \text{if } g(\bar{p}_1, \dots, \bar{p}_k)(\bar{q}_1, \dots, \bar{q}_l) = \top \end{cases}$$

*Proof.* To prove that  $(h, g)$  is in  $\mathcal{L}_{\alpha \rightarrow \beta}$ , we resort to the remark we made in the proof of Lemma 15, so that it suffices to show that for every  $p_1, \dots, p_k$  respectively in  $\mathcal{K}_{\alpha_1}, \dots, \mathcal{K}_{\alpha_k}$ ,  $(h(p_1, \dots, p_k), g(\bar{p}_1, \dots, \bar{p}_k))$  is in  $\mathcal{L}_{\alpha}$ . We have that  $h(p_1, \dots, p_k) = \left( \overline{\text{fix}_{\beta}(f(p_1, \dots, p_k))} \right)^{\uparrow}$  that is in  $\mathcal{K}_{\beta}$ , and we have that

$$\begin{aligned} \overline{h(p_1, \dots, p_k)} &= \overline{\left( \overline{\text{fix}_{\alpha}(f(p_1, \dots, p_k))} \right)^{\uparrow}} \\ &= \text{fix}_{\alpha}(\overline{f(p_1, \dots, p_k)}) \\ &= \text{fix}_{\alpha}(\bar{f}(\bar{p}_1, \dots, \bar{p}_k)) \text{ by successive use of Lemma 10} \\ &= g(\bar{p}_1, \dots, \bar{p}_k) \end{aligned}$$

This shows that  $(h, g)$  is in  $\mathcal{L}_{\alpha \rightarrow \beta}$  and thus  $h$  is in  $\mathcal{K}_{\alpha \rightarrow \beta}$ .

So as to complete the proof of the lemma, we first prove the following claim: for every  $r$  in  $\mathcal{D}_{\gamma_1 \rightarrow \dots \rightarrow \gamma_n \rightarrow \delta}$ , and  $q_1, \dots, q_n$  in  $\mathcal{K}_{\gamma_1}, \dots, \mathcal{K}_{\gamma_n}$  we have that:

- if  $r^{\uparrow}(q_1, \dots, q_n) = \perp$  then  $(r(\bar{q}_1, \dots, \bar{q}_n))^{\uparrow} = (\perp, Q_{\Omega})$ ,
- if  $r^{\uparrow}(q_1, \dots, q_n) = \top$  then  $(r(\bar{q}_1, \dots, \bar{q}_n))^{\uparrow} = (\top, Q)$ .

We first remark that, given  $r$  in  $\mathcal{D}_{\gamma \rightarrow \delta}$ , from the fourth item of Proposition 3, we have that whenever  $(q, e)$  is in  $\mathcal{L}_{\gamma}$ , then  $r^{\uparrow}(q) = (r(e))^{\uparrow}$ , so that in particular  $r^{\uparrow}(q) = (r(\bar{q}))^{\uparrow}$ . A simple induction shows then that, for  $r$  in  $\mathcal{D}_{\gamma_1 \rightarrow \dots \rightarrow \gamma_n \rightarrow \delta}$ ,

$$r^{\uparrow}(q_1, \dots, q_n) = (r(\bar{q}_1, \dots, \bar{q}_n))^{\uparrow}$$

Therefore if  $\delta = 0$  and  $r(\bar{q}_1, \dots, \bar{q}_n) = \perp$ , we have  $(r(\bar{q}_1, \dots, \bar{q}_n))^{\uparrow} = (\perp, Q_{\Omega})$ . Moreover, in case  $r(\bar{q}_1, \dots, \bar{q}_n) = \top$ , we have  $(r(\bar{q}_1, \dots, \bar{q}_n))^{\uparrow} = (\top, Q)$ .

Now, the lemma follows from choosing  $r = g(\bar{p}_1, \dots, \bar{p}_k)$  and remarking that we have  $(g(\bar{p}_1, \dots, \bar{p}_k))^{\uparrow} = h(p_1, \dots, p_k)$ .

As in the case of GFP-models the semantics of a Böhm tree is defined in terms of its truncations:  $\llbracket BT(M) \rrbracket_{\mathcal{K}} = \bigwedge \{ \llbracket BT(M) \downarrow_n \rrbracket_{\mathcal{K}} \mid n \in \mathbb{N} \}$ . The subtle difference is that now  $\Omega^0$  and  $\omega^0$  do not have the same meaning. Nevertheless the analog of Proposition 1 still holds in  $\mathcal{K}$ .

**Theorem 4.** *For very closed term  $M$  of type 0:  $\llbracket M \rrbracket_{\mathcal{K}} = \llbracket BT(M) \rrbracket_{\mathcal{K}}$ .*

*Proof.* First we show that  $\llbracket M \rrbracket_{\mathcal{K}} \leq \llbracket BT(M) \rrbracket_{\mathcal{K}}$ . For this, we proceed with the classical finite approximation technique. We thus define a finite approximation of the Böhm tree. *The Abstract Böhm tree up to depth  $l$*  of a term  $M$ , denoted  $ABT_l(M)$ , will be a term obtained by reducing  $M$  till it resembles  $BT(M)$  up to depth  $l$  as much as possible. We define it by induction:

- $ABT_0(M) = M$ ;
- $ABT_{l+1}(M)$  is  $M$  if  $M$  does not have head normal form otherwise it is a term  $\lambda \mathbf{x}. N_0 ABT_l(N_1) \dots ABT_l(N_k)$ , where  $\lambda \mathbf{x}. N_0 N_1 \dots N_k$  is the head normal form of  $M$ .

Since  $ABT_l(M)$  is obtained from  $M$  by a sequence of  $\beta\delta$ -reductions,  $\llbracket M \rrbracket_{\mathcal{K}} = \llbracket ABT_l(M) \rrbracket_{\mathcal{K}}$  for every  $l$ . We now show that for every term  $M$  and every  $l$ :

$$\llbracket ABT_l(M) \rrbracket_{\mathcal{K}} \leq \llbracket BT(M) \downarrow_l \rrbracket_{\mathcal{K}}.$$

Up to depth  $l$ , the two terms have the same structure as trees. We will see that the meaning of every leaf in  $ABT_l(M)$  is not bigger than the meaning of the corresponding leaf of  $BT(M) \downarrow_l$ . For leaves of depth  $l$  this is trivial since on the one hand we have a term and on the other the constant  $\omega$ . For other leaves, the terms are either identical and thus have the same interpretation or on one side we have a term without head normal form and on the other  $\Omega^0$  and thus, according to Proposition 4 also have the same interpretation.

The desired inequality  $\llbracket M \rrbracket_{\mathcal{K}} \leq \llbracket BT(M) \rrbracket_{\mathcal{K}}$  follows now directly from the definition of the semantics of  $BT(M)$  since  $\llbracket M \rrbracket_{\mathcal{K}} = \llbracket ABT_l(M) \rrbracket_{\mathcal{K}} \leq \llbracket BT(M) \downarrow_l \rrbracket_{\mathcal{K}}$  for every  $l \in \mathbb{N}$ ; and  $\llbracket BT(M) \rrbracket_{\mathcal{K}} = \bigwedge \{ \llbracket BT(M) \downarrow_l \rrbracket_{\mathcal{K}} \mid l \in \mathbb{N} \}$ .

For the inequality in the other direction, we also use a classical method that consists in working with finite unfolding of the  $Y$  combinators. Observe that if a term  $M$  does not have  $Y$  combinators, then it is strongly normalizing and the theorem is trivial. So we need be able to deal with  $Y$  combinators in  $M$ . For this we introduce new constants  $c_N$  for every subterm  $YN$  of  $M$ . The type of  $c_N$  is  $\alpha \rightarrow \beta$  if  $\beta$  is the type of  $YN$  and  $\alpha = \alpha_1 \dots \alpha_k$  is the sequence of types of the sequence of free variables  $\mathbf{x} = x_1 \dots x_k$  occurring in  $YN$ . We let the semantics of a constant  $c_N$  be

$$\llbracket c_N \rrbracket_{\mathcal{K}} = \lambda \mathbf{p}. \left( \text{fix}_{\beta} \left( \overline{\llbracket N \rrbracket_{\mathcal{D}}^{[\mathbf{p}/\mathbf{x}]}} \right) \right)^{\uparrow}.$$

First we need to check that indeed  $\llbracket c_N \rrbracket_{\mathcal{K}}$  is in  $\mathcal{K}$ . For this we have prepared Lemma 18. Indeed  $\llbracket c_N \rrbracket_{\mathcal{K}} = \lambda p_1 \dots p_k. \left( \text{fix}_{\beta} \left( f(p_1, \dots, p_k) \right) \right)^{\uparrow}$ , for  $f = \lambda \mathbf{p}. \llbracket N \rrbracket_{\mathcal{D}}^{[\mathbf{p}/\mathbf{x}]}$ .

So  $\llbracket c_N \rrbracket_{\mathcal{K}}$  is  $h$  from Lemma 18 and  $\llbracket c_N \rrbracket_{\mathcal{D}} = \overline{\llbracket c_N \rrbracket_{\mathcal{K}}}$  is  $g$  from that lemma. The lemma additionally gives us that for every  $p_1, \dots, p_k, q_1, \dots, q_l$ :

$$\llbracket c_N \rrbracket_{\mathcal{K}}(p_1, \dots, p_k)(q_1, \dots, q_l) = \begin{cases} (\perp, Q_{\Omega}) & \text{if } \llbracket c_N \rrbracket_{\mathcal{D}}(\bar{p}_1, \dots, \bar{p}_k)(\bar{q}_1, \dots, \bar{q}_l) = \perp \\ (\top, Q) & \text{if } \llbracket c_N \rrbracket_{\mathcal{D}}(\bar{p}_1, \dots, \bar{p}_k)(\bar{q}_1, \dots, \bar{q}_l) = \top \end{cases} \quad (2)$$

We now define term  $iterate^n(N)$  for very  $n \in \mathbb{N}$ .

$$\begin{aligned} iterate^0(N) &= c_N \mathbf{x} \\ iterate^{n+1}(N) &= N(iterate^n(N)) . \end{aligned}$$

where  $\mathbf{x}$  is the vector of variables free in  $N$ . Notice that when replacing  $c_n$  in  $iterate^n(N)$  by  $\lambda \mathbf{x}.YN$  we obtain a term that is  $\beta\delta$ -convertible to  $YN$ .

From the definition of the fixpoint operator in  $\mathcal{K}$  and the fact that  $\mathcal{K}_{\beta}$  is finite it follows that  $\llbracket \lambda \mathbf{x}.iterate^n(N) \rrbracket = \llbracket \lambda \mathbf{x}.YN \rrbracket$  for some  $n$ . Now we can apply this identity to all fixpoint subterms in  $M$  starting from the innermost subterms. So the term  $expand^i(M)$  is obtained by repeatedly replacing occurrences of subterms of the form  $YN$  in  $M$  by  $iterate^i(N)$  starting from the innermost occurrences. We get that for  $n$  chosen as above  $\llbracket M \rrbracket_{\mathcal{K}} = \llbracket expand^n(M) \rrbracket_{\mathcal{K}}$ .

We come back to the proof. The missing inequality will be obtained from

$$\llbracket M \rrbracket_{\mathcal{K}} = \llbracket expand^n(M) \rrbracket_{\mathcal{K}} = \llbracket BT(expand^n(M)) \rrbracket_{\mathcal{K}} \geq \llbracket BT(M) \rrbracket_{\mathcal{K}} .$$

The first equality we have discussed above. The second is trivial since  $expand^n(M)$  does not have fixpoints. To finish the proof it remains to show  $\llbracket BT(expand^n(M)) \rrbracket_{\mathcal{K}} \geq \llbracket BT(M) \rrbracket_{\mathcal{K}}$ .

Let us denote  $BT(expand^n(M))$  by  $P$ . So  $P$  is a term of type 0 in a normal form without occurrences of  $Y$ . For a term  $K$  let  $\tilde{K}$  stand for a term obtained from  $K$  by simultaneously replacing  $c_N$  by  $\lambda \mathbf{x}.YN$ . Because of Lemma 12, we have  $\llbracket c_N \rrbracket_{\mathcal{K}} \geq \llbracket \lambda \mathbf{x}.YN \rrbracket_{\mathcal{K}}$  which also implies that  $\llbracket K \rrbracket_{\mathcal{K}} \geq \llbracket \tilde{K} \rrbracket_{\mathcal{K}}$ . Moreover, as we have remarked above that replacing  $c_n$  in  $iterate^n(N)$  by  $\lambda \mathbf{x}.YN$  gives a term  $\beta\delta$ -convertible to  $YN$ , we have that  $\tilde{P}$  is  $\beta\delta$ -convertible to  $M$ . It then follows that  $BT(\tilde{P}) = BT(M)$ . We need to show that  $\llbracket P \rrbracket_{\mathcal{K}} \geq \llbracket BT(\tilde{P}) \rrbracket_{\mathcal{K}}$ .

Let us compare the trees  $BT(P)$  and  $BT(\tilde{P})$  by looking on every path starting from the root. The first difference appears when a node  $v$  of  $BT(P)$  is labeled with  $c_N$  for some  $N$ . Say that the subterm of  $P$  rooted in  $v$  is  $c_N K_1 \dots K_i$ . Then at the same position in  $BT(\tilde{P})$  we have the Böhm tree of the term  $(\lambda \mathbf{x}.YN)\tilde{K}_1 \dots \tilde{K}_i$ . Observe that both terms are closed and of type 0. We will be done if we show that  $\llbracket c_N K_1 \dots K_i \rrbracket_{\mathcal{K}} \geq \llbracket BT((\lambda \mathbf{x}.YN)\tilde{K}_1 \dots \tilde{K}_i) \rrbracket_{\mathcal{K}}$ .

We reason by cases. If  $\llbracket c_N K_1 \dots K_i \rrbracket_{\mathcal{D}} = \top$  then equation (2) gives us  $\llbracket c_N K_1 \dots K_i \rrbracket_{\mathcal{K}} = (\top, Q)$ . So the desired inequality holds since  $(\top, Q)$  is the greatest element of  $\mathcal{K}_0$ .

If  $\llbracket c_N K_1 \dots K_i \rrbracket_{\mathcal{D}} = \perp$  then  $\llbracket c_N \tilde{K}_1 \dots \tilde{K}_i \rrbracket_{\mathcal{D}} = \perp$  since  $\llbracket K_i \rrbracket_{\mathcal{K}} \geq \llbracket \tilde{K}_i \rrbracket_{\mathcal{K}}$ . By equation (2) we get  $\llbracket c_N \tilde{K}_1 \dots \tilde{K}_i \rrbracket_{\mathcal{D}} = (\perp, Q_{\Omega})$ . Since, by the definition of the fixpoint operator,  $\llbracket c_N \rrbracket_{\mathcal{K}} \geq \llbracket \lambda \mathbf{x}.YN \rrbracket_{\mathcal{K}}$  we get  $\llbracket YN \tilde{K}_1 \dots \tilde{K}_i \rrbracket_{\mathcal{K}} = (\perp, Q_{\Omega})$ . But then Proposition 4 implies that  $YN \tilde{K}_1 \dots \tilde{K}_i$  is unsolvable. Thus  $\llbracket BT((\lambda \mathbf{x}.YN)\tilde{K}_1 \dots \tilde{K}_i) \rrbracket_{\mathcal{K}} = \llbracket \Omega \rrbracket_{\mathcal{K}} = (\perp, Q_{\Omega})$ .

**Theorem 5.** *Let  $\mathcal{A}$  be an insightful TAC automaton with the set of states  $Q$ , initial state  $q^0$ , and  $Q_\Omega$  the set of states from which  $\mathcal{A}$  accepts  $\Omega$ . Let  $\mathcal{K} = \mathcal{K}(Q, Q_\Omega)$  be a model as in Definition 10. For every closed term  $M$  of type 0:*

$$BT(M) \in L(\mathcal{A}) \quad \text{iff} \quad q^0 \text{ is in the second component of } \llbracket M \rrbracket_{\mathcal{K}}.$$

*Proof.* For the left to right implication suppose that  $\mathcal{A}$  accepts  $BT(M)$ . Since, by Theorem 4,  $\llbracket M \rrbracket = \llbracket BT(M) \rrbracket$  it is enough to show that  $q^0$ , that is the initial state of  $\mathcal{A}$ , is in the second component of  $\llbracket BT(M) \rrbracket$ . For this we show that  $q^0$  is in the second component of  $\llbracket BT(M) \downarrow_l \rrbracket$  for every  $l \in M$ .

The tree  $BT(M)$  is a ranked tree labeled with constants from the signature. The run of  $\mathcal{A}$  is function  $r$  assigning to every node a state of  $\mathcal{A}$ . The tree  $BT(M) \downarrow_l$  is a prefix of this tree containing nodes up to depth  $l$ . Let us call it  $t_l$ . Every node  $v$  in the domain of  $t_l$  corresponds to a subterm of  $BT(M) \downarrow_l$  that we denote  $M_v^l$ .

By induction on the height of  $v$  we show that  $r(v)$  appears in the second component of  $\llbracket M_v^l \rrbracket$ . If  $v$  is a leaf at depth  $l$  then  $M_v^l$  is  $\omega^0$ . We are done since  $\llbracket \omega^0 \rrbracket = (\top, Q)$ . If  $v$  is a leaf of depth smaller than  $l$  then  $M_v^l$  is  $\Omega^0$  or a constant  $c$  of type 0. In the later case by definition of a run, we have  $r(v) \in \{q \mid \delta(q, c) = tt\}$ . We are done by the semantics of  $c$  in the model. If  $M_v^l$  is  $\Omega^0$  then  $\llbracket M_v^l \rrbracket = (\perp, Q_\Omega)$  and  $r(v)$  belongs to  $Q_\Omega$  by definition of the run. The last case is when  $v$  is an internal node of the tree  $t_l$ . In this case  $M_v^l = aM_{v_1}^l M_{v_2}^l$  where  $a$  is the constant labeling  $v$  in  $t_l$ . By induction assumption we have that  $r(v_i)$  appears in the second component of  $\llbracket M_{v_i}^l \rrbracket$ , and we are done by using the semantics of  $a$ .

For the direction from right to left we suppose that  $q^0$  in the second component of  $\llbracket M \rrbracket$ . By Theorem 4,  $\llbracket M \rrbracket = \llbracket BT(M) \rrbracket$ . We will construct a run of  $\mathcal{A}$  on  $BT(M)$ .

If  $M$  does not have head normal form then  $\llbracket M \rrbracket = (\perp, Q_\Omega)$  by Proposition 4. In this case  $BT(M)$  is the tree consisting only of the root labeled  $\Omega^0$ . Hence  $q^0 \in Q_\Omega$  and we are done.

Otherwise  $BT(M)$  has some letter  $a$  in the root. In case it is a leaf, the conclusion is immediate. In case it is a binary symbol, since  $q^0$  is in the second component of  $\llbracket BT(M) \rrbracket$ , it is also in the second component of  $\llbracket BT(M) \downarrow_l \rrbracket$  for all  $l$ . We know that  $BT(M) \downarrow_l$  is of the form  $aN_1^l N_2^l$  for some  $N_1^l, N_2^l$ . As  $\delta_{\mathcal{A}}(q^0, a)$  is a finite set of pairs, there is a pair  $(q_1, q_2) \in \delta_{\mathcal{A}}(q^0, a)$  such that  $q_1$  is in the second component of  $\llbracket M_1^l \rrbracket$  and  $q_2$  is in the second component of  $\llbracket M_2^l \rrbracket$  for infinitely many  $l$ . We put  $r(1) = q_1$  and  $r(2) = q_2$  and repeat the argument starting from the nodes 1 and 2 respectively. It is easy to see that this inductive procedure gives a, potentially infinite, run of  $\mathcal{A}$ . Hence  $BT(M) \in L(\mathcal{A})$  as every run of  $\mathcal{A}$  is accepting.

## 5 Reflection

The idea behind the notion of a reflecting term is that at every moment of its evaluation every subterm should know its meaning. Knowing the meaning amounts to extra labelling of constants. Formally, we express this by the notion

of a reflective Böhm tree defined below. The definition can be made more general but we will be interested only in the case of terms of type 0. In this section we will show that reflective Böhm trees can be generated by  $\lambda Y$ -terms.

As usual we suppose that we are working with a tree signature  $\Sigma$ . We will also need a signature where constants are annotated with elements of the model. If  $\mathcal{S} = \langle \{\mathcal{S}_\alpha\}_{\alpha \in \mathcal{T}}, \rho \rangle$  is a finitary model then the extended signature  $\Sigma^{\mathcal{S}}$  contains constants  $a^s$  where  $a$  is a constant in  $\Sigma$  and  $s \in \mathcal{S}_0$ ; so semantic annotations are possible interpretations of terms of type 0 in  $\mathcal{S}$ .

**Definition 11.** *Let  $\mathcal{S}$  be a finitary model and  $M$  a closed term of type 0,  $rBT_{\mathcal{S}}(M)$ , the reflective Böhm tree of  $M$  with respect to  $\mathcal{S}$ , is obtained in the following way:*

- If  $M \rightarrow_{\beta\delta}^* bN_1N_2$  for some constant  $b : 0 \rightarrow 0 \rightarrow 0$  then  $rBT_{\mathcal{S}}(M)$  is a tree having the root labelled by  $b^{\llbracket bN_1N_2 \rrbracket_s}$  and having  $rBT_{\mathcal{S}}(N_1)$  and  $rBT_{\mathcal{S}}(N_2)$  as subtrees.
- If  $M \rightarrow_{\beta\delta}^* c$  for some constant  $c : 0$  then  $rBT_{\mathcal{S}}(M) = c^{\llbracket c \rrbracket_s}$ .
- Otherwise,  $M$  is unsolvable and  $rBT(M) = \Omega^0$ .

Observe that when  $\mathcal{S}$  satisfies  $\llbracket N \rrbracket_{\mathcal{S}} = \llbracket BT(N) \rrbracket_{\mathcal{S}}$  for every term  $N$  then the semantic annotations in  $rBT_{\mathcal{S}}(M)$  associate their meanings to each subtree of  $rBT_{\mathcal{S}}(M)$ . When, moreover,  $\mathcal{S}$  recognizes a given property then these superscripts determine if the tree satisfies the property. These two conditions are fulfilled by the models we have considered in this paper.

We will use terms to generate reflective Böhm trees.

**Definition 12.** *Let  $\Sigma$  be a tree signature, and  $\mathcal{S}$  a finitary model. Let  $M$  be a closed term of type 0 over the signature  $\Sigma$ . We say that a term  $M'$  over the signature  $\Sigma^{\mathcal{S}}$  is a reflection of  $M$  in  $\mathcal{S}$  if  $BT(M') = rBT(M)$ .*

The objective of this section is to construct reflections of terms. Since  $\lambda Y$ -terms can be translated to schemes and vice versa, the construction would work for schemes too. (Translations between schemes and  $\lambda Y$ -terms that do not increase the type order are presented in [SW12]).

Let us fix a tree signature  $\Sigma$  and a finitary model  $\mathcal{S}$ . For the construction of reflective terms we enrich the  $\lambda Y$ -calculus with some syntactic sugar. Consider a type  $\alpha$ . The set  $\mathcal{S}_\alpha$  is finite for every type  $\alpha$ ; say  $\mathcal{S}_\alpha = \{d_1, \dots, d_k\}$ . We will introduce a new atomic type  $[\alpha]$  and constants  $d_1, \dots, d_k$  of this type; there will be no harm in using the same names for constants and elements of the model. We do this for every type  $\alpha$  and consider terms over this extended type discipline. Notice that there are no other closed normal terms than  $d_1, \dots, d_k$  of type  $[\alpha]$ .

Given a term  $M$  of type  $[\alpha]$  and  $M_1, \dots, M_n$  which are all terms of type  $\beta$ , we introduce the construct

$$\text{case}^\beta M \{d_i \rightarrow M_i\}_{d_i \in \mathcal{S}_\alpha}$$

which is a term of type  $\beta$  and which reduces to  $M_i$  when  $M = d_i$ . This construct is simple syntactic sugar since we may represent the term  $d_i$  of type  $[\alpha]$  with the

$i^{\text{th}}$  projection  $\lambda x_1 \dots x_n . x_i$  by letting  $[\alpha] = 0^k \rightarrow 0$  then, when  $\beta = \beta_1 \rightarrow \dots \rightarrow \beta_n \rightarrow 0$ ,  $\text{case}^\beta$  can be defined as the  $\lambda$ -term

$$\lambda y_1^{\beta_1} \dots y_n^{\beta_n} . d^{[\alpha]} f_1^\beta \dots f_k^\beta . d(f_1 y_1 \dots y_n) \dots (f_k y_1 \dots y_n) .$$

When  $M$  represents  $d_i$ , *i.e.* is equal to  $\lambda x_1 \dots x_n . x_i$ , the term

$$\lambda y_1^{\beta_1} \dots y_n^{\beta_n} . M(M_1 y_1 \dots y_n) \dots (M_k y_1 \dots y_n)$$

is  $\beta\eta$ -convertible to  $M_i$  which represents well the semantic of the  $\text{case}^\beta$  construct. In the sequel, we shall omit the type annotation on the case construct.

We define a transformation on types  $\alpha^\bullet$  by induction on their structure as follows:

$$\begin{aligned} \alpha^\bullet &= \alpha \text{ when } \alpha \text{ is atomic} \\ (\alpha \rightarrow \beta)^\bullet &= \alpha^\bullet \rightarrow [\alpha] \rightarrow \beta^\bullet \end{aligned}$$

The translation we are looking for will be an instance of a more general translation  $[M, v]$  of a term  $M$  of type  $\alpha$  into a term of type  $\alpha^\bullet$ , where  $v$  is a valuation over  $\mathcal{S}$ .

$$\begin{aligned} [\lambda x^\alpha . M, v] &= \lambda x^{\alpha^\bullet} \lambda y^{[\alpha]} . \\ &\quad \text{case } y^{[\alpha]} \{ d \rightarrow [M, v[d/x^\alpha]] \}_{d \in \mathcal{S}_\alpha} \\ [MN, v] &= [M, v] [N, v] \llbracket N \rrbracket^v \\ [a, v] &= \lambda x_1^0 \lambda y_1^{[0]} \lambda x_2^0 \lambda y_2^{[0]} . \\ &\quad \text{case } y_1^{[0]} \{ d_1 \rightarrow \text{case } y_2^{[0]} \{ d_2 \rightarrow a^{\rho(a)d_1 d_2} x_1 x_2 \}_{d_2 \in \mathcal{S}_0} \}_{d_1 \in \mathcal{S}_0} \\ [x^\alpha, v] &= x^{\alpha^\bullet} \\ [Y^{(\alpha \rightarrow \alpha) \rightarrow \alpha} M, v] &= Y^{(\alpha^\bullet \rightarrow \alpha^\bullet) \rightarrow \alpha^\bullet} (\lambda x^{\alpha^\bullet} . [M, v] x^{\alpha^\bullet} \llbracket YM \rrbracket^v) \end{aligned}$$

To prove correctness of this translation, we need two lemmas.

**Lemma 19.** *Given a term  $M$  and a valuation  $v$ , and the terms  $N_1, \dots, N_n$  we have the following identity:*

$$[M.\sigma, v] = [M, v'] . \sigma' ,$$

where  $\sigma = [N_1/x_1^{\alpha_1}, \dots, N_n/x_n^{\alpha_n}]$  is a substitution,  $\sigma' = [[N_1, v]/x_1^{\alpha_1^\bullet}, \dots, [N_n, v]/x_n^{\alpha_n^\bullet}]$  and  $v' = v \llbracket [N_1] \rrbracket^v / x_1^{\alpha_1}, \dots, \llbracket [N_n] \rrbracket^v / x_n^{\alpha_n} \rrbracket$ .

*Proof.* We proceed by induction on the structure of  $M$ .

In case  $M$  is a variable different from the variables  $x_1^{\alpha_1}, \dots, x_n^{\alpha_n}$  or is a constant, then the result is obvious. In case  $M = x_i^{\alpha_i}$ , the conclusion also follows with no difficulty.

In case  $M = M_1M_2$  then,  $[M.\sigma, v] = [M_1.\sigma, v][M_2.\sigma, v][M_2.\sigma]^v$ , but, by induction,  $[M_1.\sigma, v] = [M_1, v'].\sigma'$ ,  $[M_2.\sigma, v] = [M_2, v'].\sigma'$ ; moreover,  $[M_2.\sigma]^v = [[M_2]]^{v'}$ . Now we have that

$$\begin{aligned} [M, v'].\sigma' &= [M_1, v'].\sigma' [M_2, v'].\sigma' [[M_2]]^{v'} \\ &= [M_1.\sigma, v] [M_2.\sigma, v] [[M_2.\sigma]^v] \\ &= [M.\sigma, v] \end{aligned}$$

In case  $M = \lambda x^\alpha.N$  (we assume that  $x^\alpha$  is different from the variables  $x_i^{\alpha_i}$  used in the substitution), then  $[\lambda x^\alpha.M.\sigma, v] = \lambda x^{\alpha \bullet} y^{[\alpha]}. \text{case } y^{[\alpha]} \{f \rightarrow M.\sigma, v[f/x^\alpha]\}_{f \in \mathcal{S}_\alpha}$ . By induction we have that, for every  $f$  in  $\mathcal{M}_\alpha$   $[M.\sigma, v[f/x^\alpha]] = [M, v'[f/x^\alpha]].\sigma'$ . But,

$$\begin{aligned} [\lambda x^\alpha.M, v'].\sigma' &= (\lambda x^{\alpha \bullet} y^{[\alpha]}. \text{case } y^{[\alpha]} \{f \rightarrow [M, v'[f/x^\alpha]]\}_{f \in \mathcal{S}_\alpha}).\sigma' \\ &= \lambda x^{\alpha \bullet} y^{[\alpha]}. \text{case } y^{[\alpha]} \{f \rightarrow [M, v'[f/x^\alpha]].\sigma'\}_{f \in \mathcal{S}_\alpha} \\ &= \lambda x^{\alpha \bullet} y^{[\alpha]}. \text{case } y^{[\alpha]} \{f \rightarrow [M.\sigma, v[f/x^\alpha]]\}_{f \in \mathcal{S}_\alpha} \\ &= [\lambda x^\alpha.M.\sigma, v] \end{aligned}$$

In case  $M = YN$ , then  $[M.\sigma, v] = Y(\lambda y^{\alpha \bullet}. [N.\sigma, v] y^{\alpha \bullet} [[M]]^v)$ . By induction, we have that  $[M.\sigma, v] = [M, v'].\sigma'$ ; furthermore,  $[[M]]^{v'} = [[M.\sigma]]^v$  so that,

$$\begin{aligned} [M, v'].\sigma' &= Y(\lambda y^{\alpha \bullet}. [N, v'] y^{\alpha \bullet} [[M]]^{v'}) .\sigma' \\ &= Y(\lambda y^{\alpha \bullet}. [N, v'] .\sigma' y^{\alpha \bullet} [[M]]^{v'}) \\ &= Y(\lambda y^{\alpha \bullet}. [N.\sigma, v] y^{\alpha \bullet} [[M.\sigma]]^v) \\ &= [M.\sigma, v] \end{aligned}$$

We can now show that the translation is compatible with head  $\beta\delta$  reduction.

**Lemma 20.** *If  $M \rightarrow_h M'$ , then  $[M, v] \rightarrow_h^+ [M', v]$ .*

*Proof.* We proceed by induction on the structure of  $M$ . We only treat the cases where  $M$  is a redex, the other cases being trivial by induction. We are left with two cases:  $M = (\lambda x^\alpha.P)Q$  and  $M = Y^{(\alpha \rightarrow \alpha) \rightarrow \alpha} P$ .

In case  $M = (\lambda x^\alpha.P)Q$ , we have that  $M' = P[Q/x^\alpha]$ , and using the Lemma 19 we have that  $[M', v] = [P, v[[Q]^v/x^\alpha]] [[Q, v]/x^\alpha]$ . But then we have

$$\begin{aligned} [M, v] &= [\lambda x^\alpha.P, v] [Q, v] [[Q]]^v \\ &= (\lambda x^{\alpha \bullet} y^{[\alpha]}. \text{case } y^{[\alpha]} \{f \rightarrow [P, v[f/x^\alpha]]\}_{f \in \mathcal{S}_\alpha}) [Q, v] [[Q]]^v \\ &\rightarrow_h^+ [P, v[[Q]^v/x^\alpha]] [[Q, v]/x^\alpha] \\ &= [M', v] \end{aligned}$$

In case  $M = Y^{(\alpha \rightarrow \alpha) \rightarrow \alpha} P$ , we have  $M' = PM$  and:

$$\begin{aligned}
[M, v] &= Y^{(\alpha^\bullet \rightarrow \alpha^\bullet) \rightarrow \alpha^\bullet} (\lambda x^{\alpha^\bullet} . [P, v] x^{\alpha^\bullet} \llbracket M \rrbracket^v) \\
&\rightarrow_h (\lambda x^{\alpha^\bullet} . [P, v] x^{\alpha^\bullet} \llbracket M \rrbracket^v) [M, v] \\
&\rightarrow_h [P, v] [M, v] \llbracket M \rrbracket^v \\
&= [PM, v] \\
&= [M', v]
\end{aligned}$$

**Corollary 2.** *Given a term  $M$  of type 0 and a valuation  $v$ ,  $M \rightarrow_h^* aM_1M_2$  iff  $[M, v] \rightarrow_h^* a \llbracket M \rrbracket^v [M_1, v] [M_2, v]$ .*

*Proof.* The direction from left to right is a simple consequence of Lemma 20. For the direction from right to left, we use the well-known fact that a  $\lambda Y$ -term has a head normal form iff it can be head-reduced to a head normal form. Let us suppose that  $[M, v]$  reduces to  $a \llbracket M \rrbracket^v P_1 P_2$  in  $k$  steps of head-reduction. There are two cases. In case  $M$  has no head normal form, then let  $P$  be a term obtained from  $M$  by  $k+1$  steps of  $\beta\delta$  reduction, in symbols  $M \rightarrow_h^{k+1} P$ . By an iterative use of Lemma 20, we must have  $[M, v] \rightarrow_h^m [P, v]$  with  $k < m$ . A contradiction since  $P$  is not a head-normal form. The second case is when  $M$  has a head-normal form. So after some number of steps of head  $\beta\delta$ -reduction we obtain  $bN_1N_2$ . A simple use of Lemma 20 gives that  $b = a$ ,  $P_1 = [N_1, v]$  and  $P_2 = [N_2, v]$ .

**Theorem 6.** *For every finitary model  $\mathcal{S}$  and a closed term  $M$  of type 0:  $BT(\llbracket M, \emptyset \rrbracket) = rBT_{\mathcal{S}}(M)$ .*

*Proof.* This is a simple consequence of Corollary 2

*Remark:* If in the model  $\mathcal{S}$  the divergence can be observed (as it is the case for GFP models and for the model  $\mathcal{K}$ , cf. Proposition 4) then in the translation above we could add the rule  $[M, v] = \Omega$  whenever  $\llbracket M \rrbracket^v$  denotes a diverging term. We would obtain a term which would always converge. A different construction for achieving the same goal is proposed in [Had12].

*Remark:* Even though the presented translation preserves the structure of a term, it makes the term much bigger due to the *case* construction in the clause for  $\lambda$ -abstraction. The blow-up is unavoidable due to complexity lower-bounds on the model-checking problem. Nevertheless, one can try to limit the use of the *case* construct. We present below a slightly more efficient translation that takes the value of the known arguments into account and thus avoids the unnecessary use of the *case* construction. For this, the translation is now parametrized also with a stack of values from  $\mathcal{S}$  so as to recall the values taken by the arguments. For the sake of simplicity, we also assume that the constants always have all their arguments (this can be achieved by putting the  $\lambda$ -term in  $\eta$ -long form). This translation is essentially obtained from the previous one by techniques of constant propagation as used in partial evaluation.

$$\begin{aligned}
[\lambda x^\alpha.M, v, d :: S] &= \lambda x^{\alpha^\bullet} y^{[\alpha]}. [M, v[d/x^\alpha], S] \\
[\lambda x^\alpha.M, v, \varepsilon] &= \lambda x^{\alpha^\bullet} y^{[\alpha]}. \text{case } y^{[\alpha]} \{d \rightarrow [M, v[d/x^\alpha], \varepsilon]\}_{d \in S_\alpha} \\
[MN, v, S] &= [M, v, \llbracket N \rrbracket^v :: S] [N, v, \varepsilon] \llbracket N \rrbracket^v \\
[a, v, d_1 :: d_2 :: \varepsilon] &= \lambda x_1^0 \lambda y_1^{[0]} \lambda x_2^0 \lambda y_2^{[0]}. a^{\llbracket a \rrbracket d_1 d_2} x_1 x_2 \\
[x^\alpha, v, S] &= x^{\alpha^\bullet} \\
[YM, v, S] &= Y [M, v, \llbracket YM \rrbracket^X :: S]
\end{aligned}$$

## 6 Conclusions

We have shown that the model-based approach to model-checking for a class of property that is wider than simply  $\Omega$ -blind TAC automata. While a priori it is more difficult to construct a finitary model than to come up with a decision procedure, in our opinion this additional effort is justified. It allows, as we show here, to use the techniques of the theory of the  $\lambda$ -calculus. It opens new ways of looking at the algorithmics of the model-checking problem. Since typing in intersection type systems [Kob09b] and step functions in models are in direct correspondence [SMGB12], the model-based approach can also benefit from all the developments in algorithms based on typing. Finally, this approach allows us to get new constructions as demonstrated by our transformation of a scheme to a scheme reflecting a given property. Observe that this transformation is general and does not depend on our particular model.

As we have seen, the model-based approach is particularly straightforward for  $\Omega$ -blind TAC automata. It uses standard observations on models of the  $\lambda Y$ -calculus and Proposition 2 with a simple inductive proof. The model we propose for insightful automata may seem involved; nevertheless, the construction is based on simple and standard techniques. Moreover, this model implements an interesting interaction between components. It succeeds in mixing a GFP model for  $\Omega$ -blind automaton with the model  $\mathcal{D}$  for detecting solvability.

The approach using models opens several new perspectives. One can try to characterize which kinds of fixpoints correspond to which class of automata conditions. More generally, models hint a possibility to have a Eilenberg like variety theory for lambda-terms [Eil74]. This theory would cover infinite regular words and trees too as they can be represented by  $\lambda Y$ -terms. Finally, considering model-checking algorithms, the model-based approach puts a focus on computing fixpoints in finite partial orders. This means that a number of techniques, ranging from under/over-approximations, to program optimization can be applied.

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