# **Transfer Theorem**

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# **TRANSFER** THEOREM For all $\varphi$ exists $\hat{\varphi}$ s.t.

### $M\vDash \widehat{\varphi} \quad \text{iff} \quad BT(M)\vDash \varphi$

**TRANSFER THEOREM** For all  $\Sigma, \mathcal{T}, \mathcal{X}$ . For all  $\varphi$  exists  $\hat{\varphi}$  s.t. for all  $M \in Terms(\Sigma, \mathcal{T}, \mathcal{X})$ :  $M \vDash \hat{\varphi}$  iff  $BT(M) \vDash \varphi$ 

### EXAMPLE: UNFOLDING

Graph 
$$\xrightarrow{unfold}$$
 Tree

MSO-COMPATIBILITY OF UNFOLDING For all  $\Sigma$ .

For all  $\varphi$  exists  $\widehat{\varphi}$  s.t. for all  $G \in Graph(\Sigma)$  :

 $G \vDash \widehat{\varphi} \quad \text{iff} \quad Unf(G) \vDash \varphi$ 

Rem: This theorem implies Rabin's Theorem.



**PCF** (Programming Computable Functions)

 $\begin{aligned} search \equiv &\lambda p: nat \to bool. \\ &\mathbf{letrec} \; f(x:nat): nat = \mathbf{if} \; (px) \; \mathbf{then} \; x \; \mathbf{else} \; f(x+1) \; \mathbf{in} \; f0 \end{aligned}$ 

- Proposed by Scott (1969)
- Mitchell "Foundations for Programming Languages" (1996): Designed to be easily analyzed, rather than practical language for writing programs. However with some syntactic sugar it is possible to write many functional programs in a comfortable style.
- PCF has been in the center of interest of semantics
  - "sequentially computable functional", parallel OR, full abstraction.

Finitary PCF: base types are finite.

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- [Statman'04]:  $\beta\delta$ -equality on terms is undecidable.
- [Loader'96]: There is no recursive fully-abstract model

Finitary PCF  $\equiv \lambda Y$ -calculus simply-typed  $\lambda$  calculus with fixpoint operators.  $map(f, l) \equiv if \ l = nil then \ nil$ else cons(f(head(l)), map(f, tail(l)))

map(f, (a, b, c)) = (f(a), f(b), f(c))

 $map(f, l) \equiv$  if l = nil then nilelse cons(f(head(l)), map(f, tail(l)))





Such trees are interesting because

- They reflect a part of the semantics of a program.
- They have decidable MSOL theory.
- Interesting properties can be expressed in MSOL:
  - All elements in the result are in the range of f

# Resource usage for functional programs [Kobayashi'09]



One can verify if usage patterns are correct.

#### WHILE-PROGRAMS

 $x := e \mid \texttt{if } x = 0 \texttt{ then } I_1 \texttt{ else } I_2 \mid \texttt{while } x > 0 \texttt{ do } I$ 

variables range over  $\mathbb N$  and e are arithmetic expressions

- While-programs are Turing powerful.
- Does this mean that all other programming concepts are obsolete?
- Schemes give a way to show that they are not:
  - There is a recursive scheme whose tree cannot be generated by a scheme of a while program.



 $F \equiv \lambda x$ . if x = 0 then 1 else  $F(x - 1) \cdot x$ .

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Thm [Courcelle PhD]:

1-st order recursive schemes  $\equiv$  deterministic pushdown automata.

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**Thm** [Courcelle PhD]: 1-st order recursive schemes  $\equiv$  deterministic pushdown automata.

**Thm** [Senizergues]: Equivalence of 1-st order schemes (in terms of trees they generate) is decidable.

Thm [Courcelle]: MSOL theory of trees generated by 1-st order schemes is decidable.

### WHAT ABOUT HIGHER-ORDER SCHEMES?

### Second-order scheme

 $Map \equiv \lambda f.\lambda x.$  if x = nil then nil else  $f(hd(x)) \cdot Map(f, tl(x))$ 

**Thm** [Knapik, Niwiński, Urzyczyn]: Higher-order safe schemes  $\equiv$  higher-order pushdown automata

**Theorem** [Hague, Murawski, Ong & Serre]: n-th order schemes  $\equiv$  unfoldings of n-th order collapse pushdown automata.

Thm [Parys]: Safety is a true restriction

HERE:

On MSO theories of trees generated by higher-order schemes (These are also the tress generated by programs of finitary PCF).



#### Languages, Higher-order pushdowns

#### + Aho'68 indexed languages

+ Maslov'74 '76 higher-order indexed languages and higher order pushdown automata.

- + Courcelle'76 for trees: 1-st order schemes=CFL
- + Engelfriet Schmidt'77 10/01
- + Damm'82 for languages: rec schemes= higher-order pusdowns
- + Kanpik Niwinski Urzyczyn'02 Safe schemes = higher-order pusdown
- + Senizergues'97 Equivalence of 1st order schemes is decidable +Statman'04 Equivalence of PCE terms is undecidable
  - +Loader'01: Lambda-definability is undecidable
- + Ong'06: Decidability of MSOL theory

### Two main algorithmic problems



### Deciding equality of schemes:

Do two schemes generate the same trees? Deciding MSOL theory for schemes:

Does a given MSOL formula hold in a tree generated by a scheme?

Ad equality: Decidable for schemes of order 1 [Senizergues] Ad MSOL: Decidable [Ong] The model-checking problem:

Given S and an MSOL formula  $\varphi$  decide if  $\llbracket S \rrbracket \vDash \varphi$ .

**Theorem**[Ong]: This problem is decidable.



### MOTIVATION

- Finitary PCF is an important abstraction of functional languages.
- Finitary PCF  $\equiv$  schemes  $\equiv \lambda Y$ -calculus.
- It has been studied by semantics and language communities since 60'ties.
- The "schematological" approach to semantics gives non-trivial insights and without (sometimes) sacrificing decidability.

**Objective :** Understanding trees generated by PCF programs

# **TRANSFER** THEOREM For all $\varphi$ exists $\hat{\varphi}$ s.t.

### $M\vDash \widehat{\varphi} \quad \text{iff} \quad BT(M)\vDash \varphi$

**TRANSFER THEOREM** For all  $\Sigma, \mathcal{T}, \mathcal{X}$ . For all  $\varphi$  exists  $\hat{\varphi}$  s.t. for all  $M \in Terms(\Sigma, \mathcal{T}, \mathcal{X})$ :  $M \vDash \hat{\varphi}$  iff  $BT(M) \vDash \varphi$ 

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Rem: This theorem implies Rabin's Theorem.

### EXAMPLE: NORMALIZABLE TERMS

TRANSFER THEOREM

```
For all \varphi exists \widehat{\varphi} s.t. for all M \in Terms(\Sigma, \mathcal{T}, \mathcal{X}):
```

 $M \vDash \widehat{\varphi} \quad \text{iff} \quad BT(M) \vDash \varphi$ 

• Take  $\varphi \equiv$  "finite tree"

•  $BT(M) \vDash \varphi$  iff *M* has a normal form.

 $M \vDash \widehat{\varphi}$  iff M has a normal form

So  $\{M \in Terms(\Sigma, \mathcal{T}, \mathcal{X}) : M \text{ has a normal form}\}$  is MSOL-definable.

 $M \xrightarrow{eval} BT(M)$ 

# $\lambda Y$ -terms

Types: 0 is a type, and  $\alpha \rightarrow \beta$  is a type if  $\alpha, \beta$  types.

Tree signature  $\Sigma = \{a, b, ...\}$  all constants of type  $0 \to 0 \to 0$ .

TERMS

 $\Omega^{\alpha}, x^{\alpha}, \mathbf{x}^{\alpha}, \text{ or } c^{\alpha} \text{ are in } \mathcal{T}_{\alpha}.$ 



$$\begin{array}{l} \lambda^{\alpha \to \beta} \\ \downarrow \\ \mathcal{T}_{\beta} \end{array} \quad \text{is in } \mathcal{T}_{\alpha \to \beta}. \\ \\ Y^{\alpha} \mathbf{x} \\ \downarrow \\ \mathcal{T}_{\alpha} \end{array} \quad \text{is in } \mathcal{T}_{\alpha}. \end{array}$$



 $M \xrightarrow{eval} BT(M)$ 

### Evaluation and BT(M)

- $\beta$ -reduction  $(\lambda x.M)N \rightarrow_{\beta} M[x := N].$
- $\delta$ -reduction  $Y\mathbf{x}.M \rightarrow_{\delta} M[\mathbf{x} := Y\mathbf{x}.M].$
- Head redex:  $(\lambda x.P)P_0 \dots P_n$  or  $(Y\mathbf{x}.P)P_1 \dots P_n$
- Weak head normal form:  $hN_1 \dots N_k$  with h a variable or a constant different than  $\Omega$ .

### Böhm tree

Suppose that M: 0 over a tree signature.

• if  $M \to_h^* bN_1N_2$  with  $b \neq \Omega$  then BT(M) =

$$\begin{array}{c}
 b \\
 \swarrow \\
 BT(N_1) \quad BT(N_2)
\end{array}$$

• otherwise  $BT(M) = \Omega^0$ .

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#### Example 1

- Y**x**.a**x**
- Every tree generated by a recursive scheme is BT(M) for some M.

EXAMPLE 2 (QBF)

- $tt = \lambda xy. x$ ,  $ff = \lambda xy. y$ ,
- and  $= \lambda b_1 b_2 xy$ .  $b_1(b_2 xy)y$ ,
- $neg = \lambda bxy. byx$

They are of type  $0 \rightarrow 0 \rightarrow 0$ . or  $= \lambda b_1 b_2 xy. \ b_1 x (b_2 xy),$ 

• All =  $\lambda f$ . and(f tt)(f ff), Exists =  $\lambda f$ . or(f tt)(f ff).

#### QBF TO TERMS

Every *QBF* formula  $\alpha$  can be translated to a term  $M_{\alpha}$ :

$$\forall x. \exists y. x \land \neg y \mapsto \mathsf{All}(\lambda x. \mathsf{Exists}(\lambda y. \mathsf{and} x (\mathsf{neg} y)))$$

**Fact** For every QBF sentence  $\alpha$ :

 $\alpha$  is true iff  $M_{\alpha}$  evaluates to tt.

```
TRANSFER THEOREM
For all \Sigma, \mathcal{T}, \mathcal{X}.
For all \varphi exists \hat{\varphi} s.t. for all M \in Terms(\Sigma, \mathcal{T}, \mathcal{X}):
```

 $M\vDash \widehat{\varphi} \quad \text{iff} \quad BT(M)\vDash \varphi$ 

- $\Sigma$  is a tree signature
- $\mathcal{T}$  is a finite set of terms
- X is a finite set of λ-variables
- $Terms(\Sigma, \mathcal{T}, \mathcal{X})$ : terms over  $\Sigma$  with
  - all subterms having type in  $\mathcal{T}$ ,
  - all  $\lambda$ -variables from  $\mathcal{X}$ .

Note: no limitation on Y variables.

### What it means $M \models \hat{\varphi}$ ?

M is represented as a graph Graph(M) over the alphabet

$$Talph(\Sigma, \mathcal{T}, \mathcal{X}) = \sum \cup \{ @^{\alpha}, Y^{\alpha}, \vdash^{\alpha} : \alpha \in \mathcal{T} \} \cup \mathcal{X} \cup \\ \{ \lambda^{\alpha \to \beta} x^{\alpha} : \alpha \in \mathcal{T} \land \alpha \to \beta \in \mathcal{T} \land x^{\alpha} \in \mathcal{X} \}.$$



# **Transfer Thm:** For all $\varphi$ exists $\widehat{\varphi}$ s.t. for all $M \in Terms(\Sigma, \mathcal{T}, \mathcal{X})$ : $M \models \widehat{\varphi} \quad \text{iff} \quad BT(M) \models \varphi$

# Consequences of the transfer theorem

### ONG'S THEOREM

It is decidable if for a given finite term M and MSOL formula  $\varphi$ ,  $BT(M) \models \varphi$  holds.

**Proof:** Just test  $M \vDash \widehat{\varphi}$ .

THE SET OF NORMALIZING TERMS IS MSOL DEFINABLE For a fixed  $\mathcal{T}$  and  $\mathcal{X}$  there is a formula defining the set of terms  $M \in Terms(\Sigma, \mathcal{T}, \mathcal{X})$  having a normal form.

**Proof:** Take  $\varphi$  defining the set of finite trees and consider  $\hat{\varphi}$ .

**QBF** TO TERMS Every *QBF* formula  $\alpha$  can be translated to a term  $M_{\alpha}$ :

 $\forall x. \exists y. \ x \land \neg y \quad \mapsto \quad All(\lambda x. \ Exists(\lambda y. \ and \ x \ (neg \ y)))$ 

 $\alpha$  is true iff  $BT(M_{\alpha})$  is the term *true* 

Take  $\varphi$  saying that the tree consists only of the root labeled *true*. Consider  $\hat{\varphi}$ .

 $M_{\alpha} \vDash \widehat{\varphi}$  iff  $\alpha$  is true.

If we could construct  $\widehat{\varphi}$  without limiting  $\mathcal{X}$  then we get collapse of the polynomial hierarchy.

#### MATCHING WITH RESTRICTED NO OF VARIABLES

For a fixed  $\mathcal{X}$ . Given M and K (without fixpoints) decide if there is a substitution  $\sigma$  such that

$$M\sigma =_{\beta} K$$

Substitution  $\Sigma$  can use only terms from  $Terms(\Sigma, \mathcal{T}, \mathcal{X})$ .

### Proof:

- Let shape(N) be MSOL formula defining the set of terms in Terms(Σ, T, X) that can be obtained from N by substitutions.
- Let  $\varphi \equiv shape(K)$ .
- There is desired  $\sigma$  iff the formula  $shape(M) \land \widehat{\varphi}$  is satisfiable.

If there is a solution then there is a finite one.

#### Synthesis from modules

Given finite  $\lambda Y$ -terms  $M_1, \ldots, M_k$  and  $\varphi$  can one construct a  $\lambda Y$  term K from these terms such that  $BT(M) \vDash \varphi$ .

### Proof:

- The candidate term K can be described as having the form  $(\lambda x_1 \dots x_k, N)M_1, \dots, M_k$  for some term N without constants and  $\lambda$ -abstractions.
- Let  $\psi$  be a formula defining terms of this form.
- There is a solution iff the formula  $\psi \wedge \widehat{\varphi}$  is satisfiable.

Every model of  $\psi \wedge \widehat{\varphi}$  gives a solution.

If there is a solution then there is a regular one, hence a finite one thanks to the presence of Y.

# **Transfer Thm:** For all $\varphi$ exists $\hat{\varphi}$ s.t. for all $M \in Terms(\Sigma, \mathcal{T}, \mathcal{X})$ : $M \models \hat{\varphi} \quad \text{iff} \quad BT(M) \models \varphi$

# A sketch of the proof

$\varphi$	$BT(M)\vDash\varphi$		$M \vDash F^{-1}(\gamma_{win})$	M
Ţ	iff		iff	$\mathbf{J}_F$
$\mathcal{A}$	$BT(M) \in L(\mathcal{A})$		$G(\mathcal{A}, M) \vDash \gamma_{win}$	$G(\mathcal{A}, M)$
	iff		iff	
	Eve wins in $\mathcal{K}(\mathcal{A}, M)$	iff	Eve wins in $G(\mathcal{A}, M)$	

### *M* is in a canonical form if no subterm Y**x**. *N* of *M* has free $\lambda$ -variables.

#### $Y\mathbf{x}. N \qquad \mapsto \qquad (Y\mathbf{y}.\lambda x_1 \dots \lambda x_n. N[\mathbf{x} := \mathbf{y}x_1 \dots x_n])x_1 \dots x_n$

### KRIVINE MACHINE

• Closure 
$$C ::= (N, \rho)$$

• Environment 
$$\rho ::= \emptyset \mid \rho[x \mapsto C]$$

Initial term

$$M = (Y\mathbf{x}^{0\to 0}.\lambda y^0.b(\mathbf{x}y)y)(Y\mathbf{z}^0.c\mathbf{z}\mathbf{z})$$

A closure

$$C = (b(\mathbf{x}y^0), [y^0 \leftarrow (Y\mathbf{z}^0.c\mathbf{z}\mathbf{z}, \emptyset)])$$

Expansion of the closure

$$E(C) = b(\mathbf{x}y^0)[y := E(Y\mathbf{z}^0.c\mathbf{z}\mathbf{z}, \emptyset)]$$

# KRIVINE MACHINE (2)

A configuration of a Krivine machine is a triple  $(N, \rho, S)$  where:

- *N* is a term (a subterm of *M*);
- $\rho$  is an environment defined for all free variables of N;
- S is a stack C<sub>1</sub>... C<sub>k</sub>, where k and the types of the closures are determined by the type of N: the type of C<sub>i</sub> is α<sub>i</sub> where the type of N is α<sub>1</sub> → ··· → α<sub>k</sub> → 0.

A configuration  $(N, \rho, S)$  represents an infinitary term:

$$E((N, \rho, S)) = E(N, \rho)E(C_1)\dots E(C_n)$$

Example:  $(b(\mathbf{x}y^0), [y^0 \leftarrow Y\mathbf{z^0}.c\mathbf{zz}], (y^0, [y^0 \leftarrow Y\mathbf{z^0}.c\mathbf{zz}]))$ 

Fix a canonical term M. Every Y-variable bound at most once in M. So  $term(\mathbf{x})$  is the subterm  $Y\mathbf{x}.N$  of M. (It has not free  $\lambda$ -vars).

KRIVINE MACHINE

$$\begin{aligned} (\lambda x.N,\rho,(K,\rho')S) &\to (N,\rho[x\mapsto (K,\rho')],S) \\ &(Y\mathbf{x}.N,\rho,S) \to (N,\rho,S) \\ &(NK,\rho,S) \to (N,\rho,(K,\rho)S) \\ &(x,\rho,S) \to (N,\rho',S) \quad \text{where } (N,\rho') = \rho(x) \\ &(\mathbf{x},\rho,S) \to (term(\mathbf{x}),\emptyset,S) \end{aligned}$$

#### Lemma

Term  $E(N, \rho, \bot)$  has a head normal form iff Krivine machine reduces  $(N, \rho, \bot)$  to a  $(b, \rho, S)$  for some constant  $b \neq \Omega$ .

## Computing Böhm tree

#### Lemma

Term  $E(N, \rho, \bot)$  has a head normal form iff Krivine machine reduces  $(N, \rho, \bot)$  to a  $(b, \rho, S)$  for some constant  $b \neq \Omega$ .



# Computing Böhm tree $(N, \rho, \bot)$ $(b, \rho', (N_1, \rho_1)(N_2, \rho_2))$ $(\bar{N}_2, \rho_2, \varepsilon)$ $(N_1, \rho_1, \varepsilon)$ $BT(N_1\rho_1)$ $BT(N_2\rho_2)$ $Ktree(N, \rho, \bot) = BT(N\rho)$

### Theorem

For every concrete canonical and closed  $\lambda Y$ -term M of type 0:

BT(M) = KT(M).

All the terms appearing in configurations of the Krivine machine during the computation of KT(M) are subterms of M.

# A sketch of the proof



### Defining $\mathcal{K}(\mathcal{A}, M)$



#### The resulting Bohm tree



Defining  $\mathcal{K}(\mathcal{A}, M)$ 



Defining  $\mathcal{K}(\mathcal{A}, M)$ 



## Definition of $\mathcal{K}(\mathcal{A}, M)$

- The root is  $q^0:(M,\emptyset,\bot)$
- A node  $q:(a,\rho,S)$  has a successor  $(q_0,q_1):(a,\rho,S)$  for every  $(q_0,q_1)\in\delta(q,a).$
- A node  $(q_0, q_1) : (a, \rho, (v_0, N_0, \rho_0)(v_1, N_1, \rho_1))$  successors  $q_0 : (N_0, \rho_0, \bot)$  and  $q_1 : (N_1, \rho_1, \bot)$ .

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- A node  $q : (\lambda x.N, \rho, CS)$  has a successor  $q : (N, \rho[x \mapsto C], S)$ .
- A node  $q : (Yx.N, \rho, S)$  has a successor  $q : (N, \rho, S)$ .
- A node  $q : (\mathbf{x}, \rho, S)$ , for  $\mathbf{x}$  a recursive variable, has a successor  $q : (term(\mathbf{x}), \emptyset, S)$ .

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- A node  $q : (\mathbf{x}, \rho, S)$ , for  $\mathbf{x}$  a recursive variable, has a successor  $q : (term(\mathbf{x}), \emptyset, S)$ .
- A node v labeled  $q : (NK, \rho, S)$  has a unique successor labeled  $q : (N, \rho, (v, K, \rho)S)$ . v-closure is created.
- A node v labeled  $q : (x, \rho, S)$ , for x a  $\lambda$ -variable and  $\rho(x) = (v', N, \rho')$ , has a unique successor labeled  $q : (N, \rho', S)$ . Node v uses a v'-closure.

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**Thm:** Eve wins in  $\mathcal{K}(\mathcal{A}, M)$  iff  $\mathcal{A}$  accepts BT(M).

# A sketch of the proof



From  $\mathcal{K}(\mathcal{A}, M)$  to  $G(\mathcal{A}, M)$ 



• Residual of type 0 is from  $\mathcal{P}(Q \times [d])$ .

• Residual of type  $0 \to 0$  is from  $\mathcal{P}(Q \times [d]) \to \mathcal{P}(Q \times [d])$ .

# $G(\mathcal{A}, M)$

$$\begin{split} q : (\lambda x.N, \rho, R \cdot S) &\to q : (N, \rho[x \mapsto R], S) \\ q : (a, \rho, R_0 R_1) \to (q_0, q_1) : (a, \rho, R_0 R_1) & \text{for } (q_0, q_1) \in \delta(q, a) \\ q : (Y \mathbf{x}.N, \rho, S) \to q : (N, \rho, S) \\ q : (\mathbf{x}, \rho, S) \to q : (term(\mathbf{x}), \rho, S) & \mathbf{x} \text{ a recursion variable} \end{split}$$

# $G(\mathcal{A}, M)$



Eve wins in a position:

- $q:(x,\rho,S)$ if  $(q,rk(q)) \in R_x(R_1,\ldots,R_k)$ ; where  $\rho(x) = R_x$  and  $S = R_1 \cdots R_k$ .
- $(q_0, q_1) : (a, \rho, R_0 R_1)$ if  $(q_0, rk(q_0)) \in R_0 \mid_{rk(q_0)}$  and  $(q_1, rk(q_1)) \in R_1 \mid_{rk(q_1)}$ .

## Properties of $G(\mathcal{A}, M)$



**Thm:** Eve wins in  $G(\mathcal{A}, M)$  iff Eve wins in  $\mathcal{K}(\mathcal{A}, M)$ .

**Obs:** For every *N* there are finitely many nodes in  $G(\mathcal{A}, M)$  containing *N*.

# A sketch of the proof



**Prop:**  $G(\mathcal{A}, M)$  is definable from in Graph(M) by means of MSOL-transduction.

# **TRANSFER THEOREM** For all $\varphi$ exists $\hat{\varphi}$ s.t. for all $M \in Terms(\Sigma, \mathcal{T}, \mathcal{X})$ : $M \models \hat{\varphi} \quad \text{iff} \quad BT(M) \models \varphi$